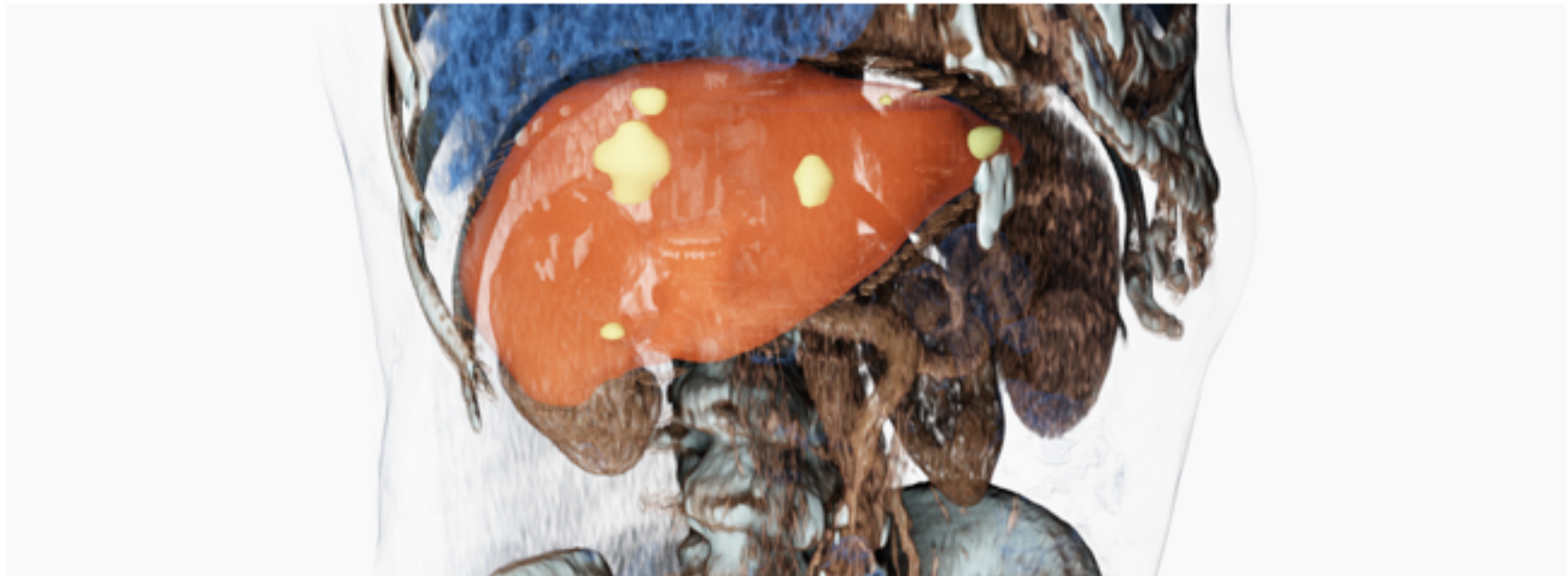
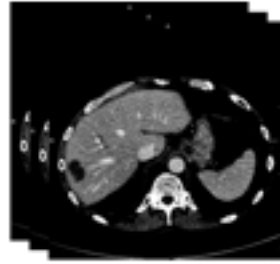

NEURAL NETWORK BASED AUTOMATIC LIVER AND LIVER TUMOR SEGMENTATION

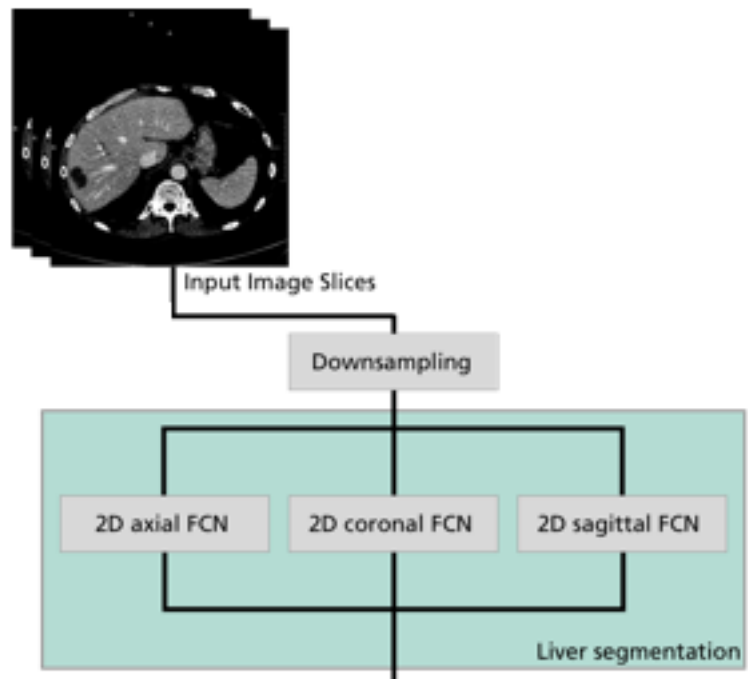
Grzegorz Chlebus, Hans Meine, Jan Hendrik Moltz, Andrea Schenk

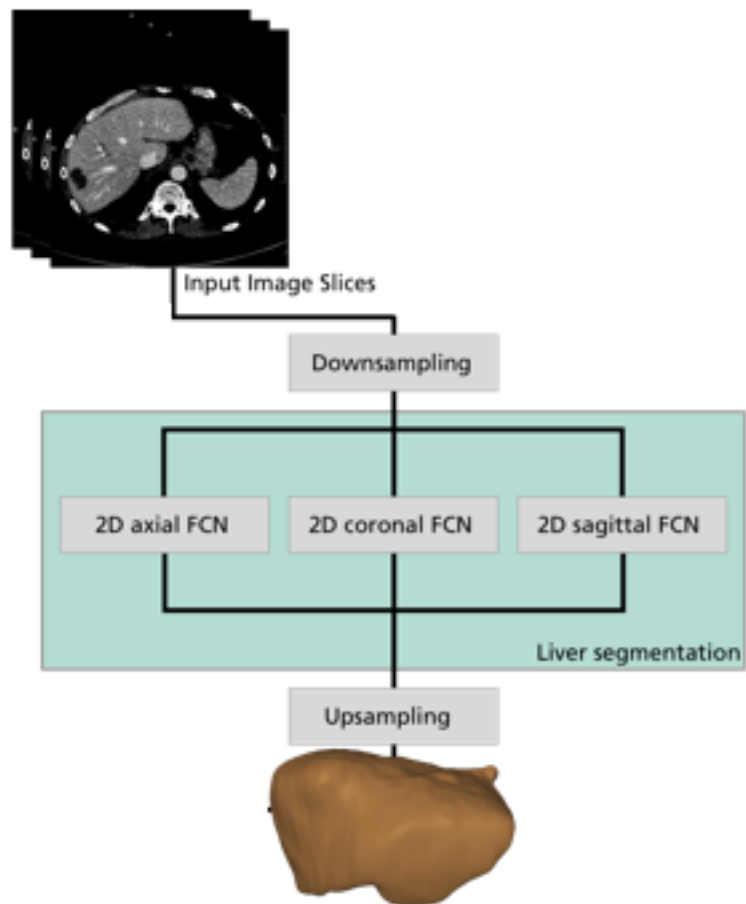


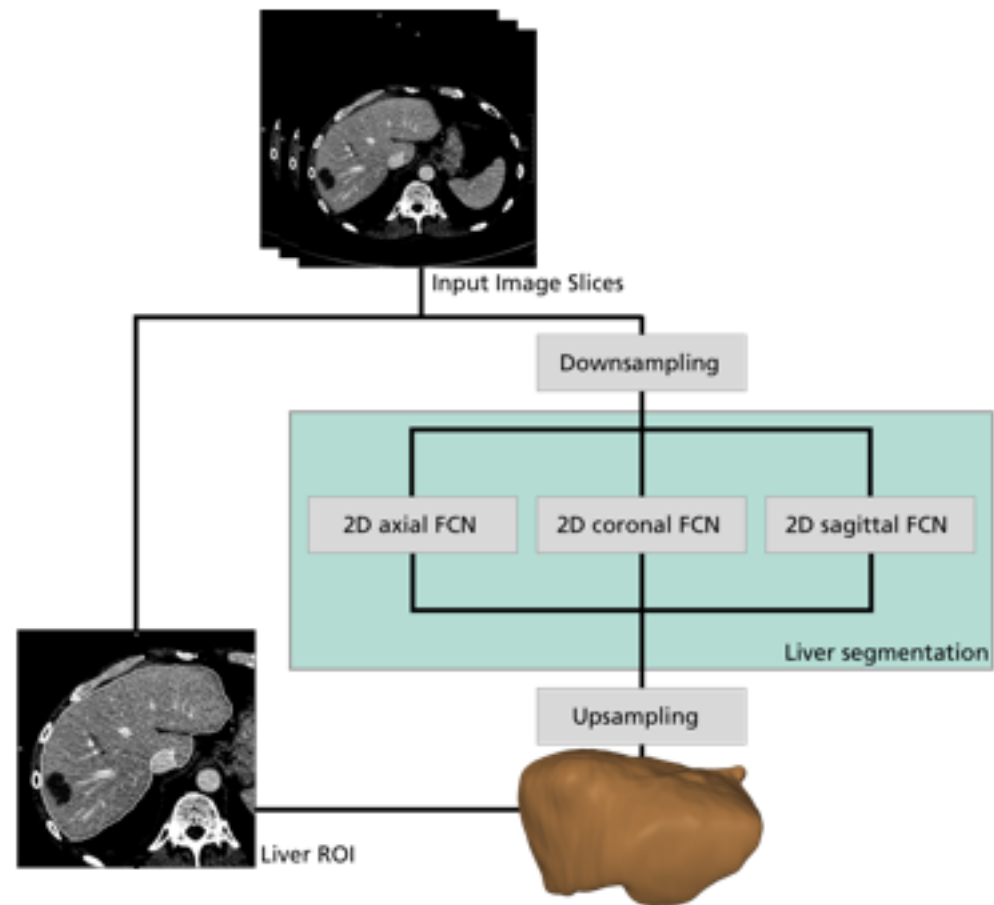
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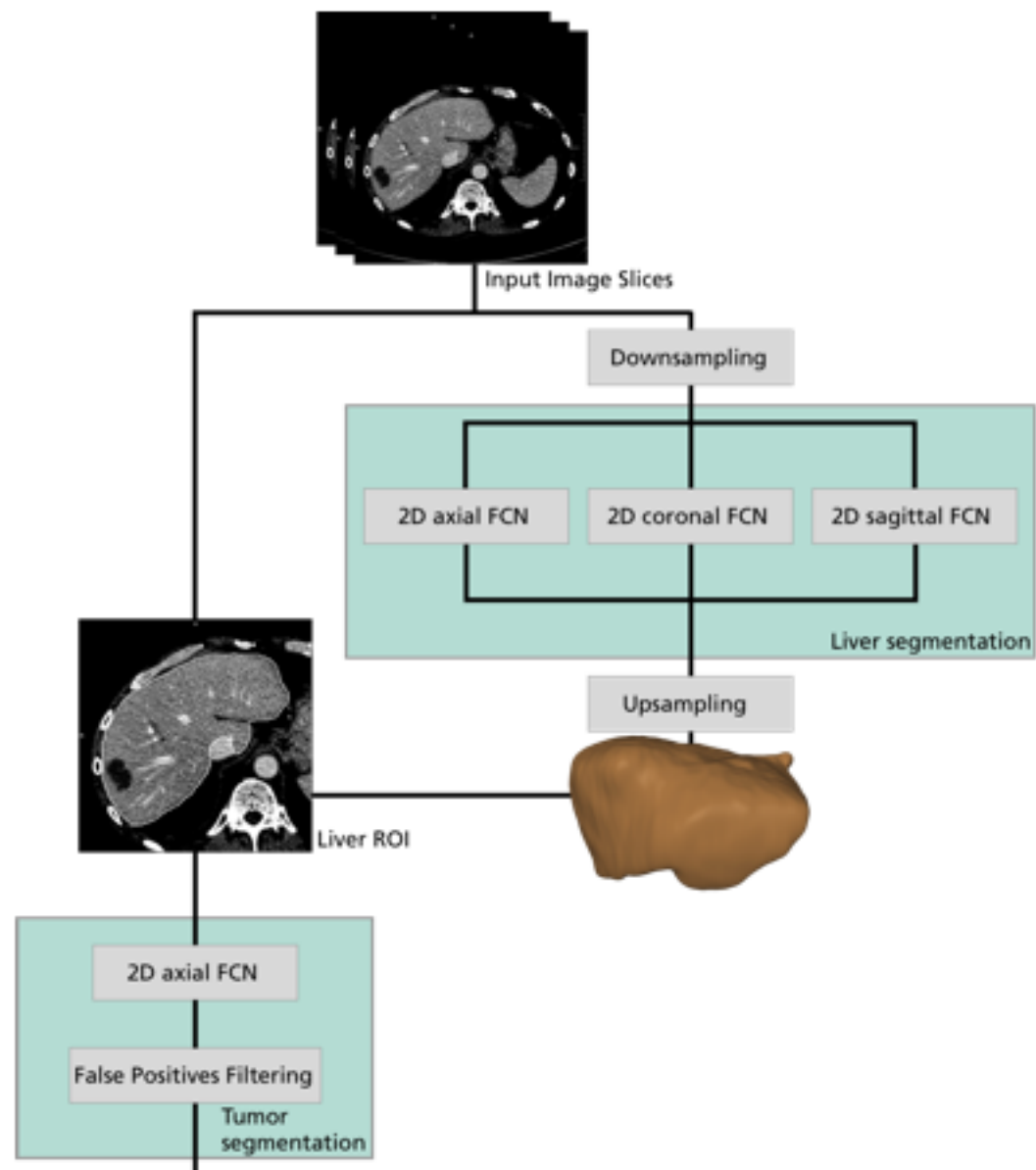


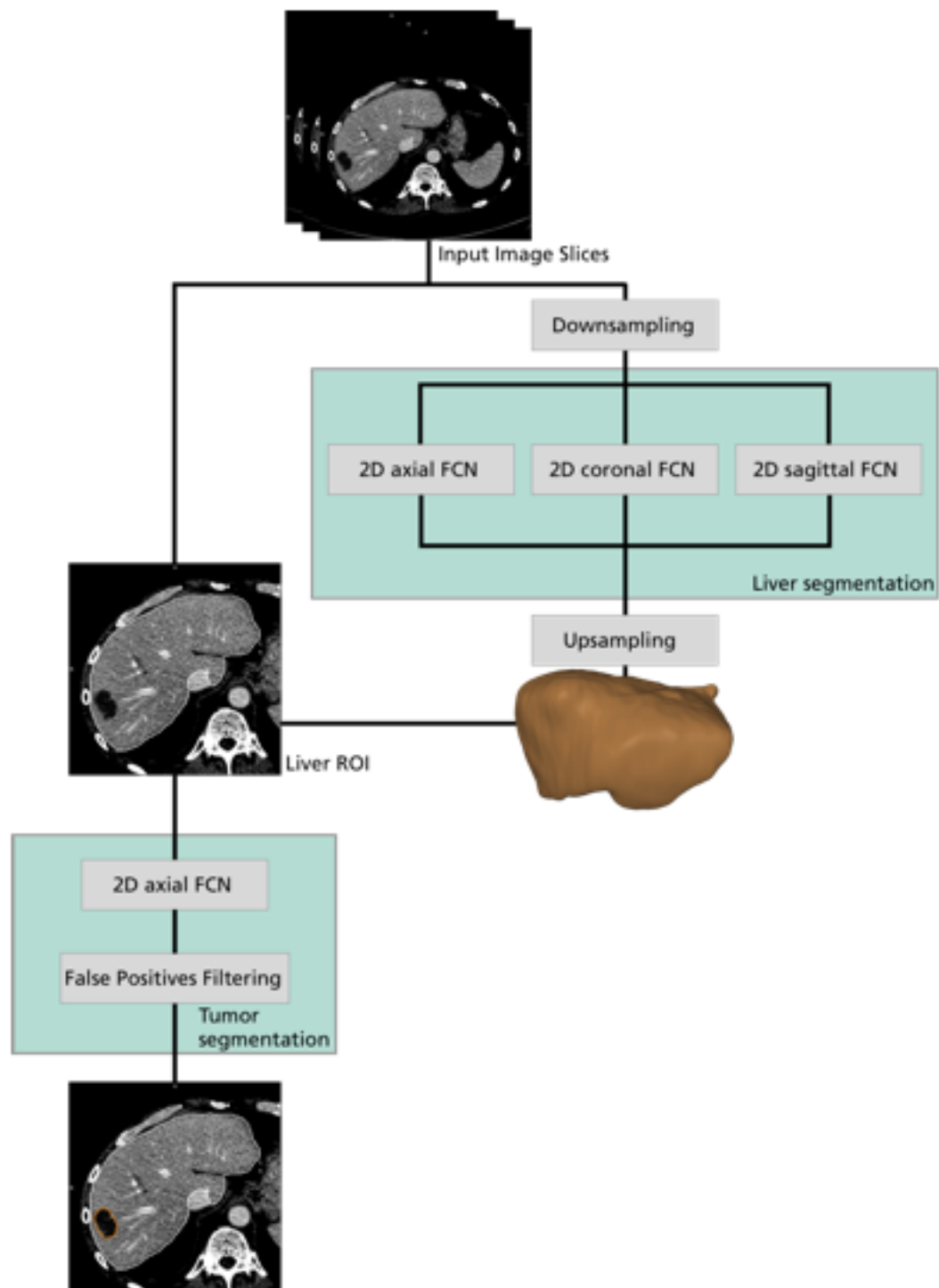
Input Image Slices











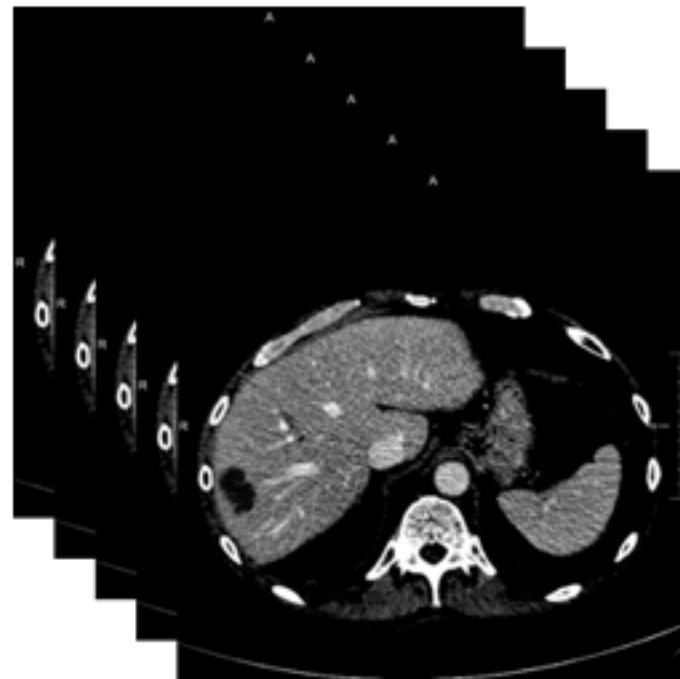
Datasets

■ LiTS

- 131 CTs:
 - 105 - training
 - 15 - validation
 - 11 - testing
- ~0.8 mm in-plane resolution
- ~1.5 mm slice thickness

■ Liver surgery planning

- 179 CTs all used for training
- ~0.6 mm in plane-resolution
- ~0.8 mm slice thickness
- Livers segmented by radiological experts



Liver Segmentation Data and Preprocessing

- Two training datasets
 - LiTS
 - Liver surgery planning
- Preprocessing
 - Rescaling raw GV to HU
 - Resampling to 2 mm isotropic voxel size
 - Padding with -1000 HU

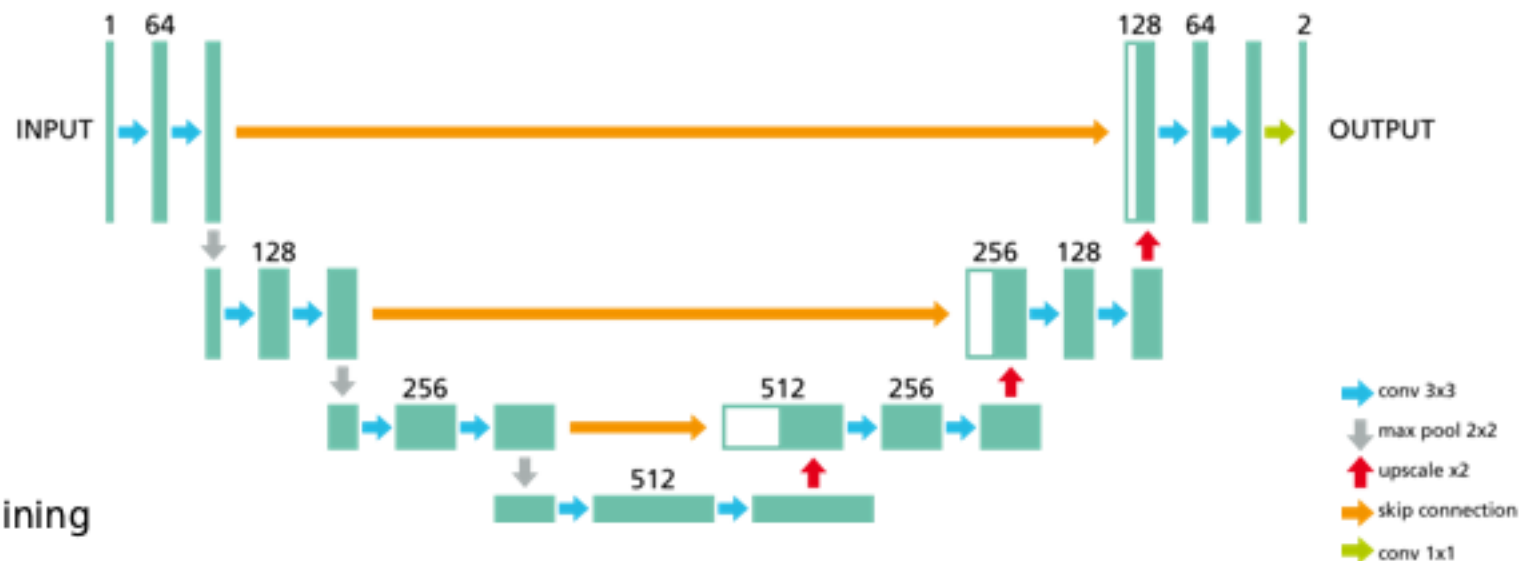
FCN General Info

- Convolution block
 - Dropout $p=0.5$ in the upscaling path
 - ReLU activation function
 - Batch normalization
- Softmax as the final layer
- Training
 - Dice loss function
 - Adam optimizer

Liver Segmentation

Network Architecture and Training

- 2D U-net [1] with 4 resolution levels



- Training

- Patch size: 148x148 (axial) or 148x44
- Batch size 15
- 10^{-5} learning rate
- ~30k iterations / ~43 epochs / ~19 h

[1] Ronneberger O. et al., "U- Net: Convolutional Networks for Biomedical Image Segmentation", 2015.

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Liver Segmentation

Postprocessing

- Biggest connected components of the majority vote mask

Liver Segmentation Postprocessing

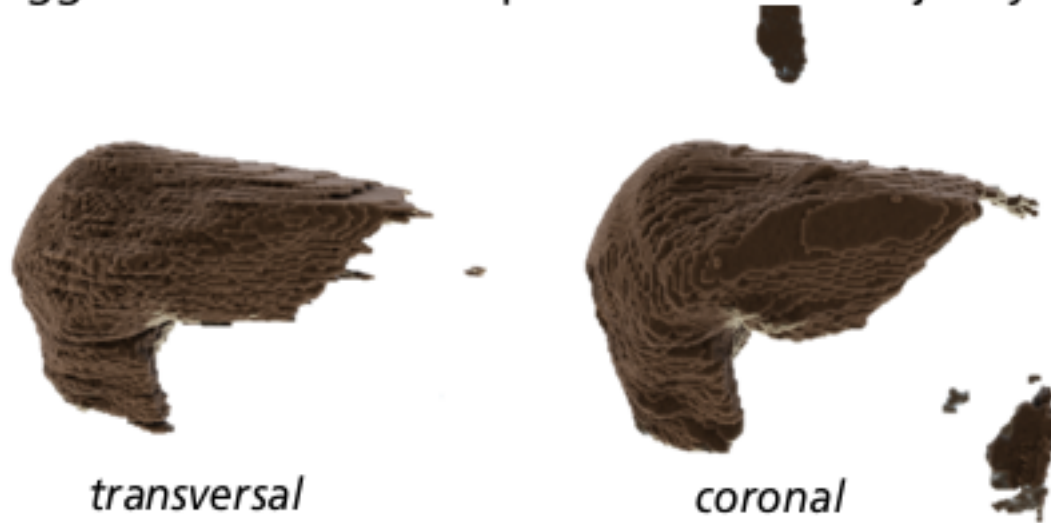
- Biggest connected components of the majority vote mask



transversal

Liver Segmentation Postprocessing

- Biggest connected components of the majority vote mask

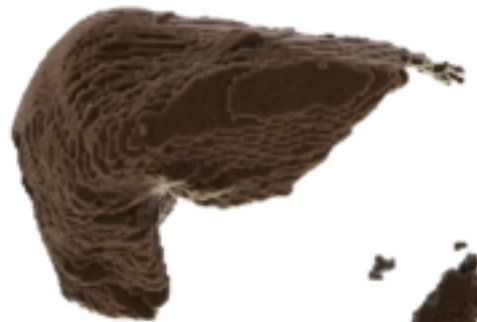


Liver Segmentation Postprocessing

- Biggest connected components of the majority vote mask



transversal



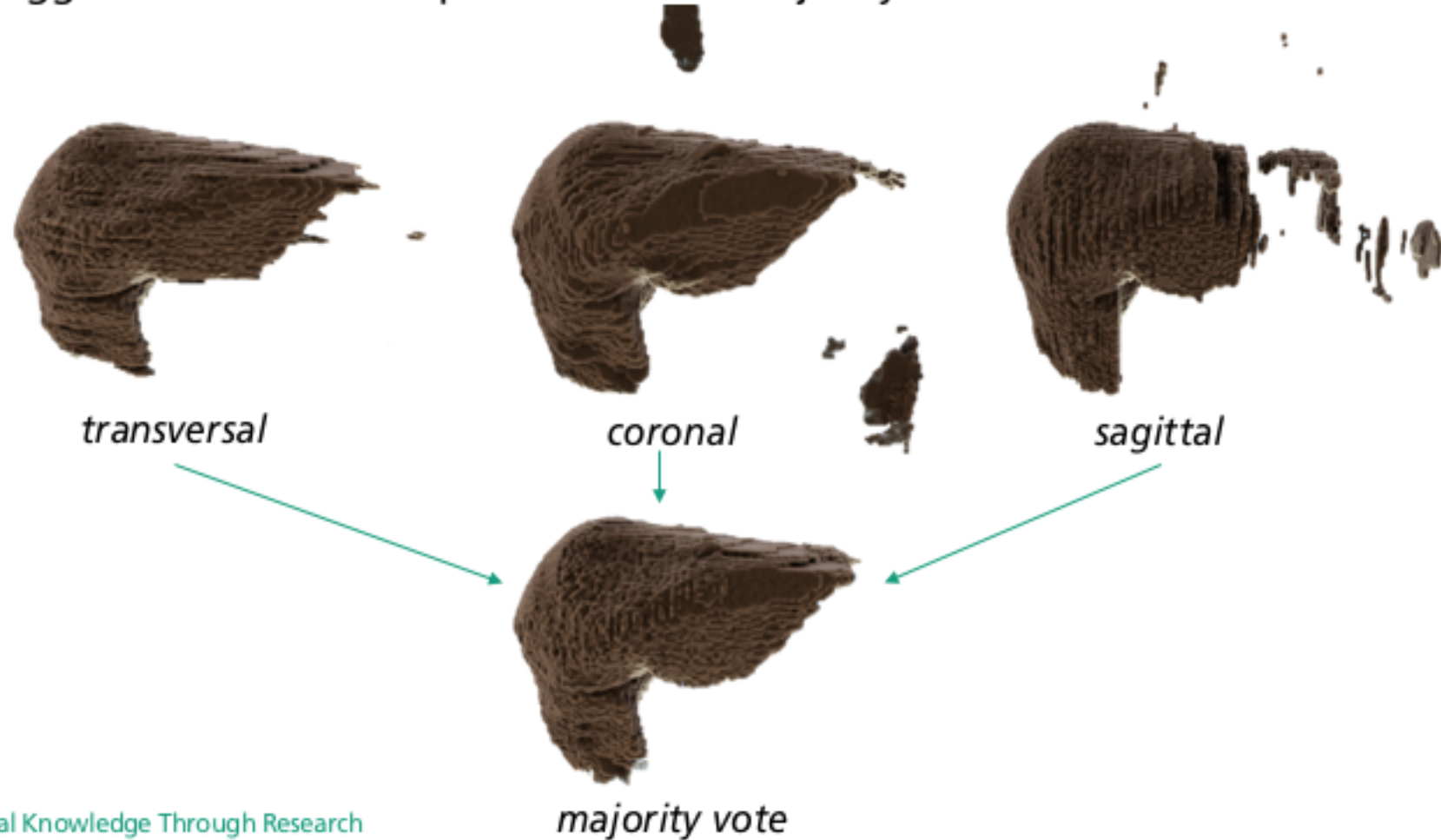
coronal



sagittal

Liver Segmentation Postprocessing

- Biggest connected components of the majority vote mask



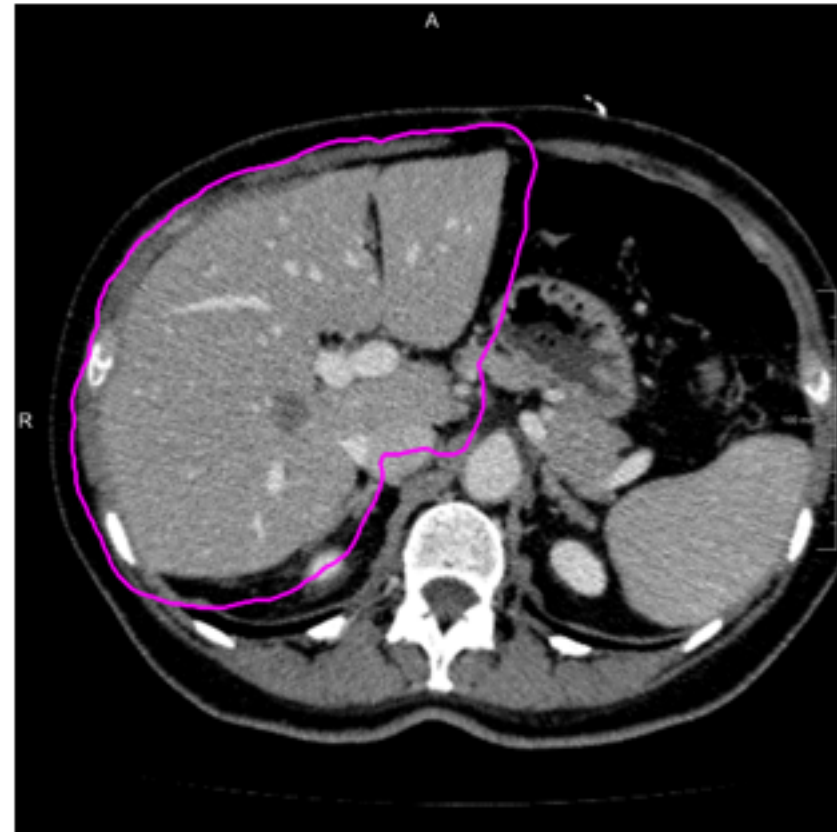
Tumor Segmentation Data and Preprocessing

- LiTS dataset
- Preprocessing
 - Padding with -1000 HU



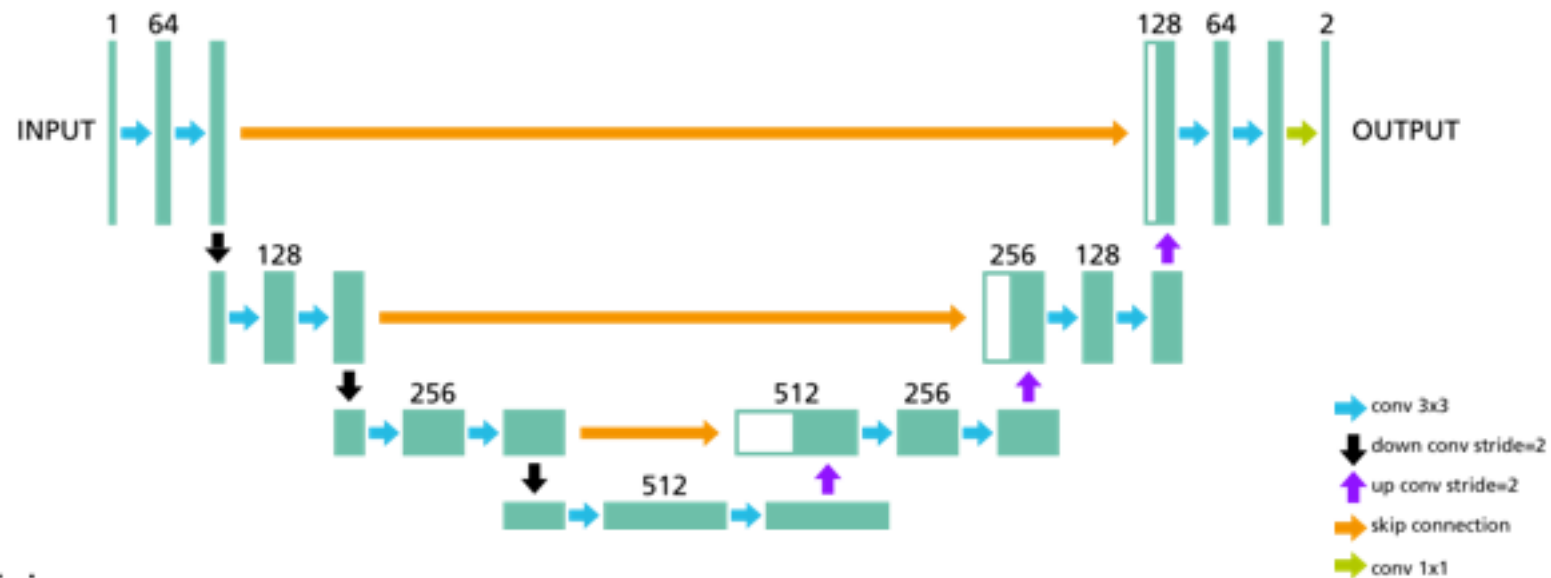
Tumor Segmentation Data and Preprocessing

- LiTS dataset
- Preprocessing
 - Padding with -1000 HU
- Masked loss



Tumor Segmentation Network Architecture and Training

- Modified 2D U-net with 4 resolution levels



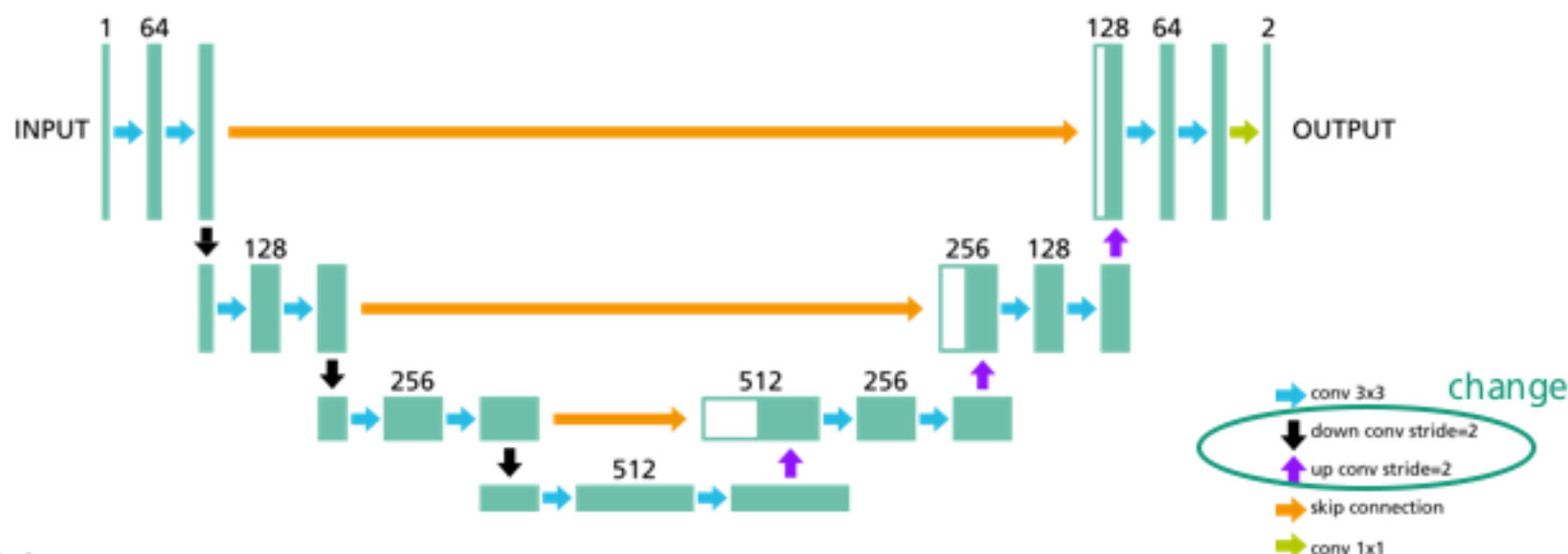
Training

- Patch size: 252x252 (axial)
- Batch size 6
- 5⁻⁵ learning rate
- Random flipping
- Only tumor patches
- ~230k iterations / ~32 epochs / ~38 h

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Tumor Segmentation Network Architecture and Training

- Modified 2D U-net with 4 resolution levels



Training

- Patch size: 252x252 (axial)
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Tumor Segmentation Output of the FCN



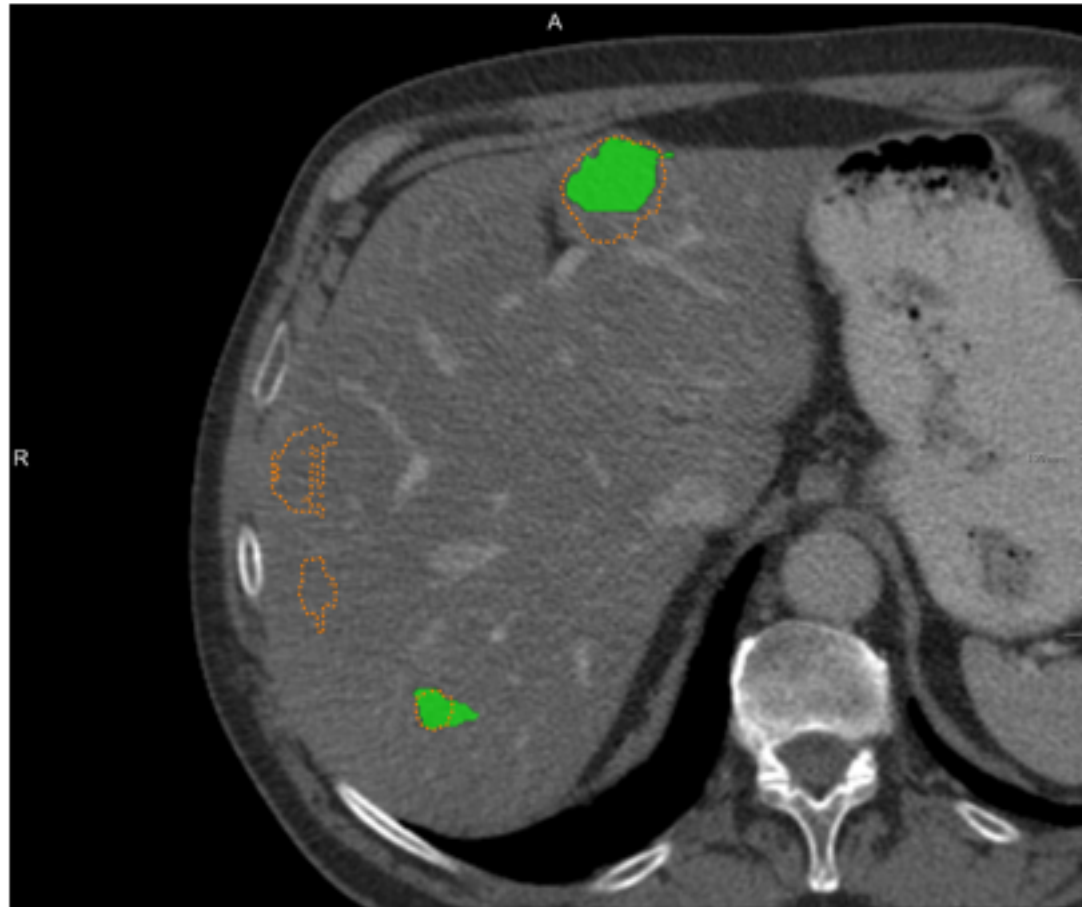
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Tumor Segmentation Output of the FCN



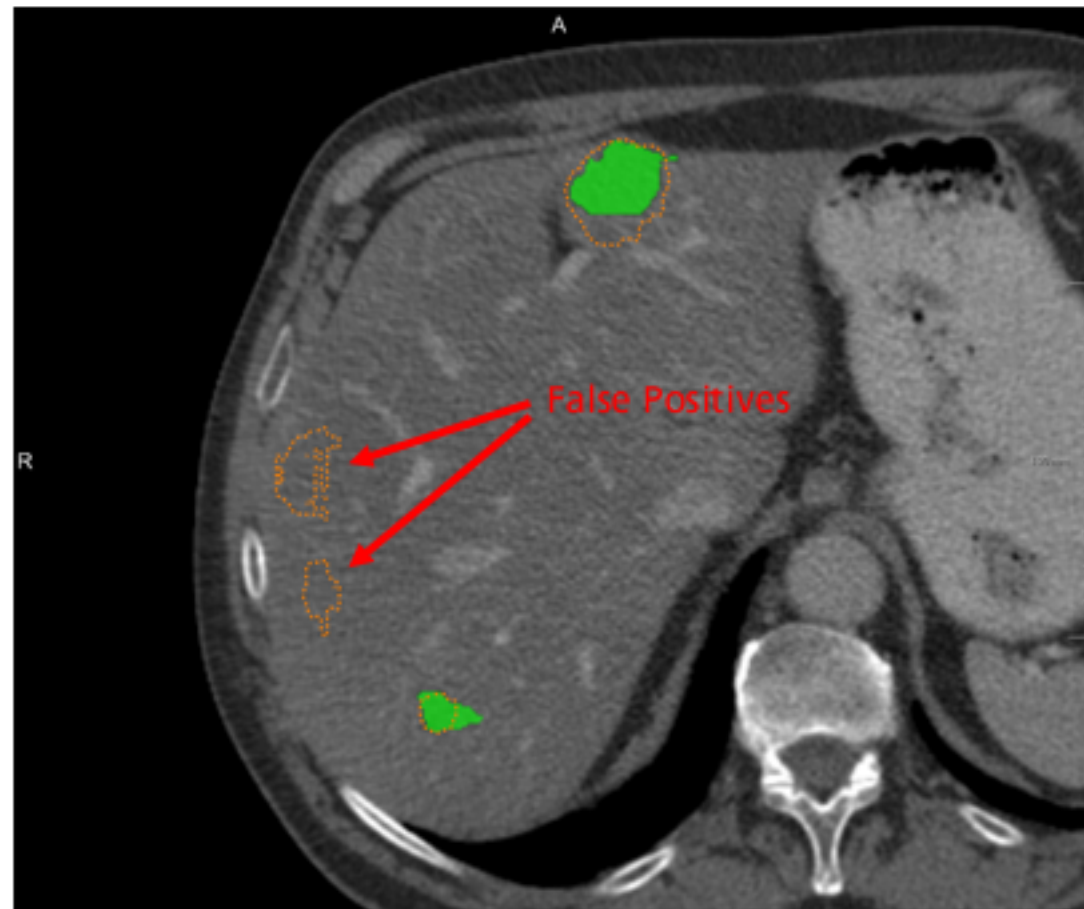
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Tumor Segmentation Output of the FCN



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Tumor Segmentation Output of the FCN



■ False Positives (FPs) Problem

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Tumor Segmentation

FPs Filtering



- Train another classifier to detect FPs
- 46 features based on:
 - CT intensity
 - Shape
 - DTF of the liver mask
- Random Forest (RF) accuracy ~90%

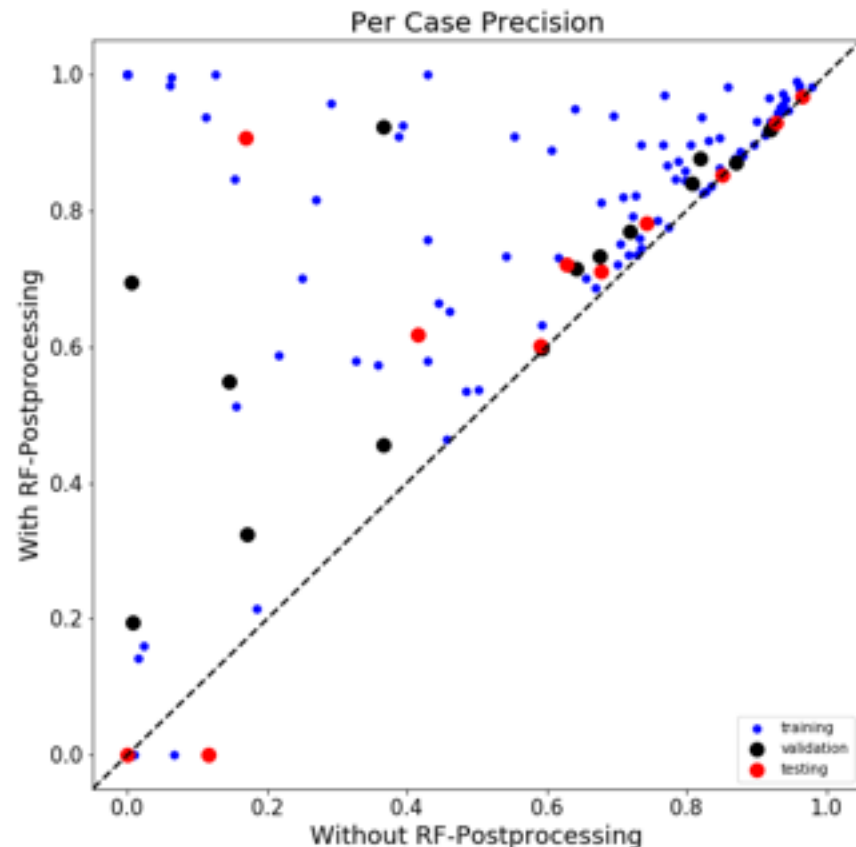
Tumor Segmentation FPs Filtering

- Train another classifier to detect FPs
- 46 features based on:
 - CT intensity
 - Shape
 - DTF of the liver mask
- Random Forest (RF) accuracy ~90%
- RF vs No-RF:
 - Recall






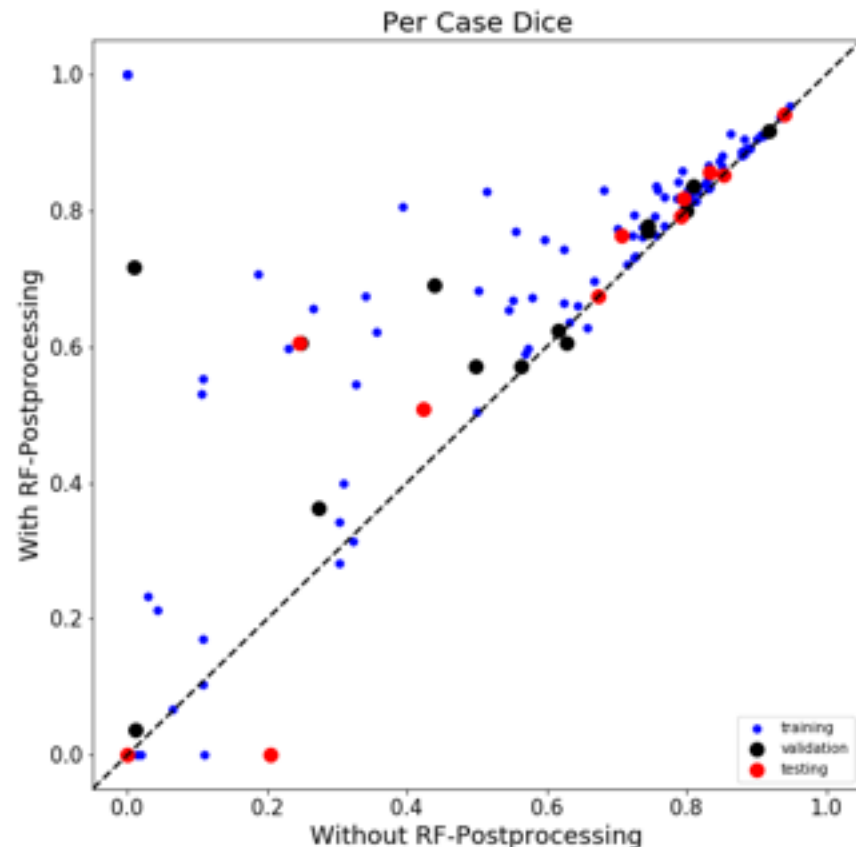
Tumor Segmentation FPs Filtering

- Train another classifier to detect FPs
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 - CT intensity
 - Shape
 - DTF of the liver mask
- Random Forest (RF) accuracy ~90%
- RF vs No-RF:
 - Recall 
 - Precision 



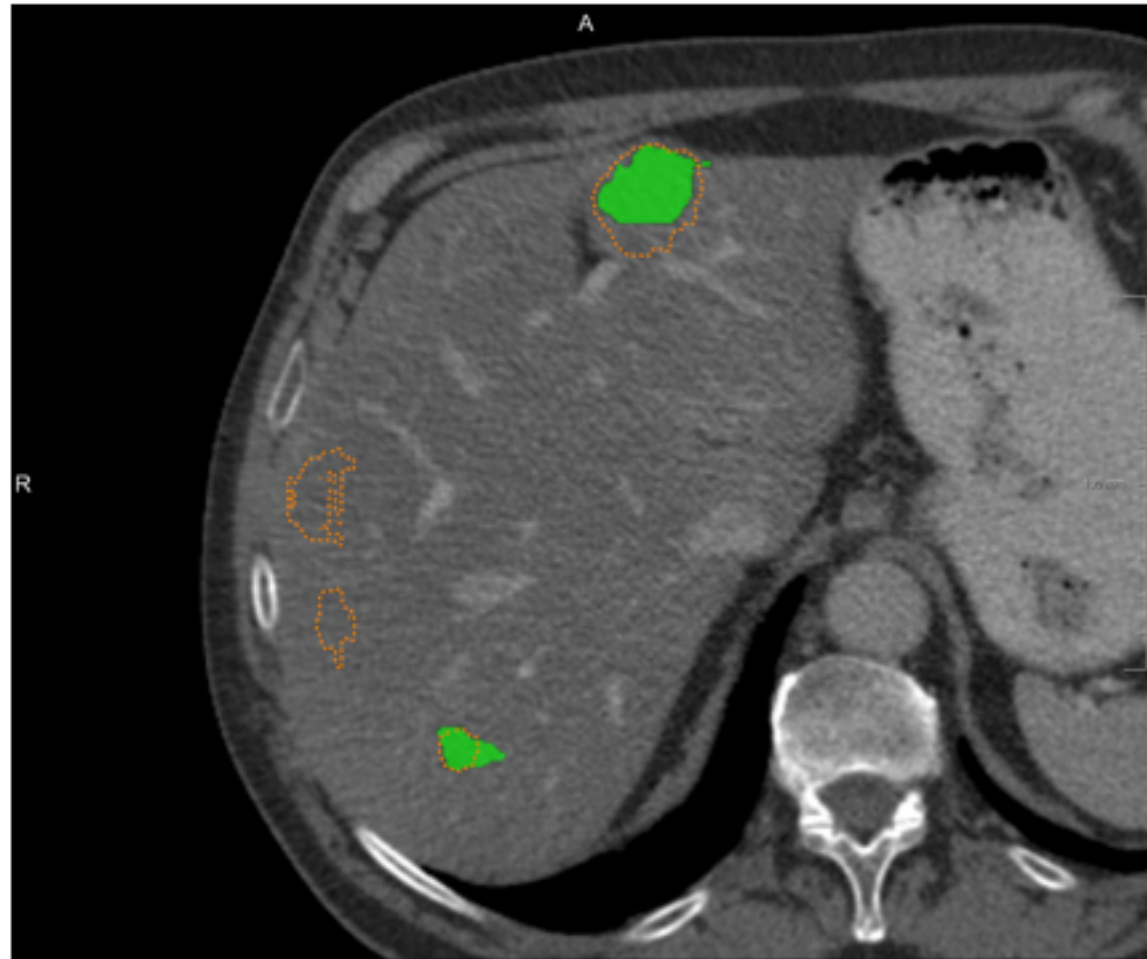
Tumor Segmentation FPs Filtering

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 - Precision 
 - Dice 



Tumor Segmentation

FPs Filtering Examples

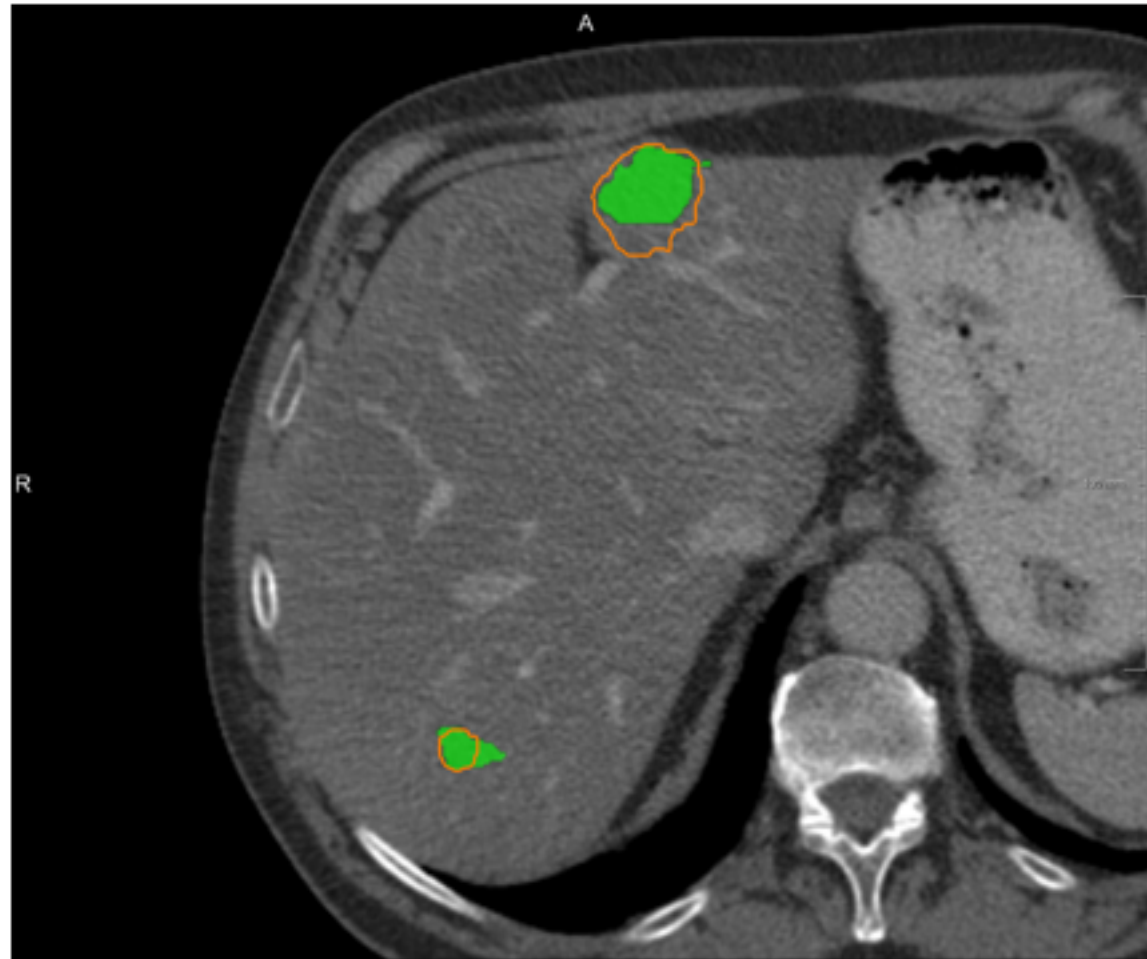


Without RF-Postprocessing

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Tumor Segmentation

FPs Filtering Examples

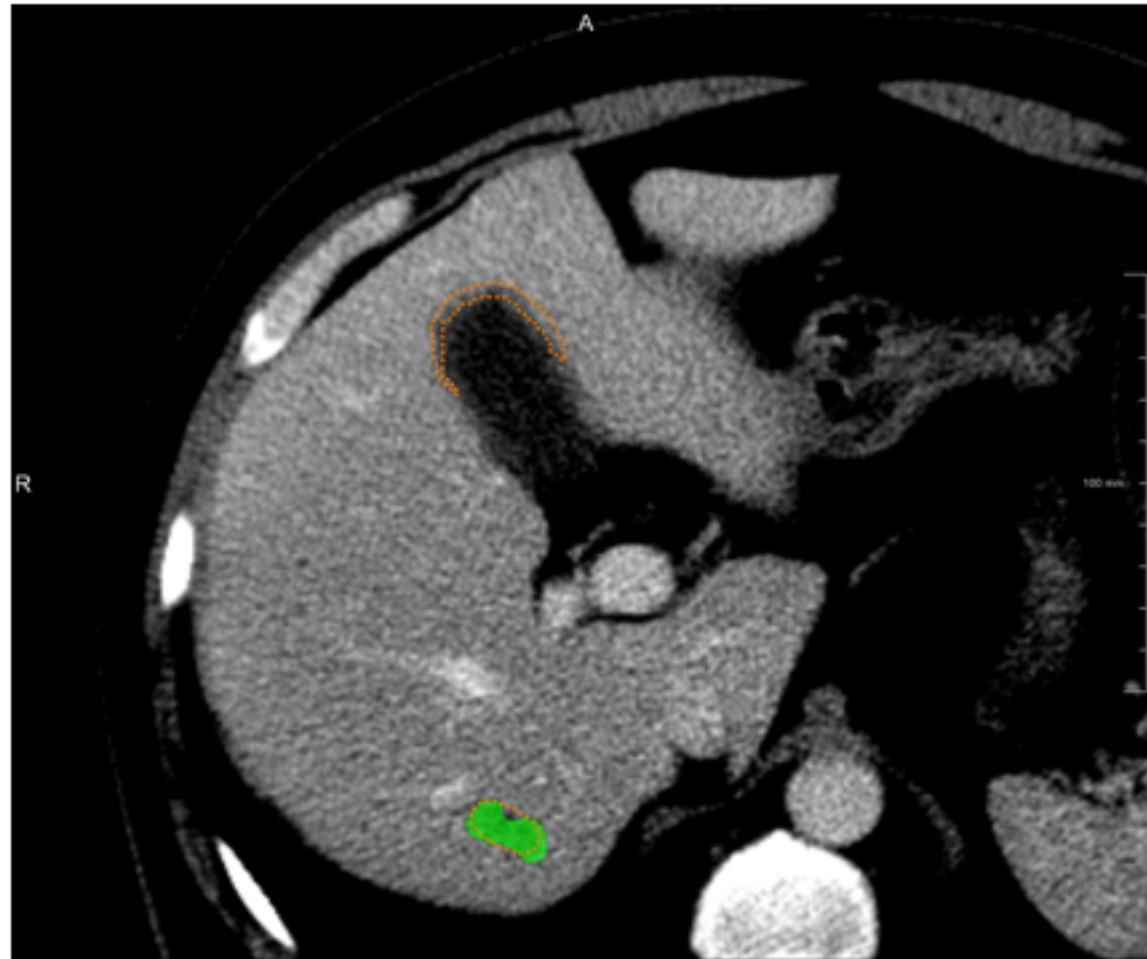


With RF-Postprocessing

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Tumor Segmentation

FPs Filtering Examples

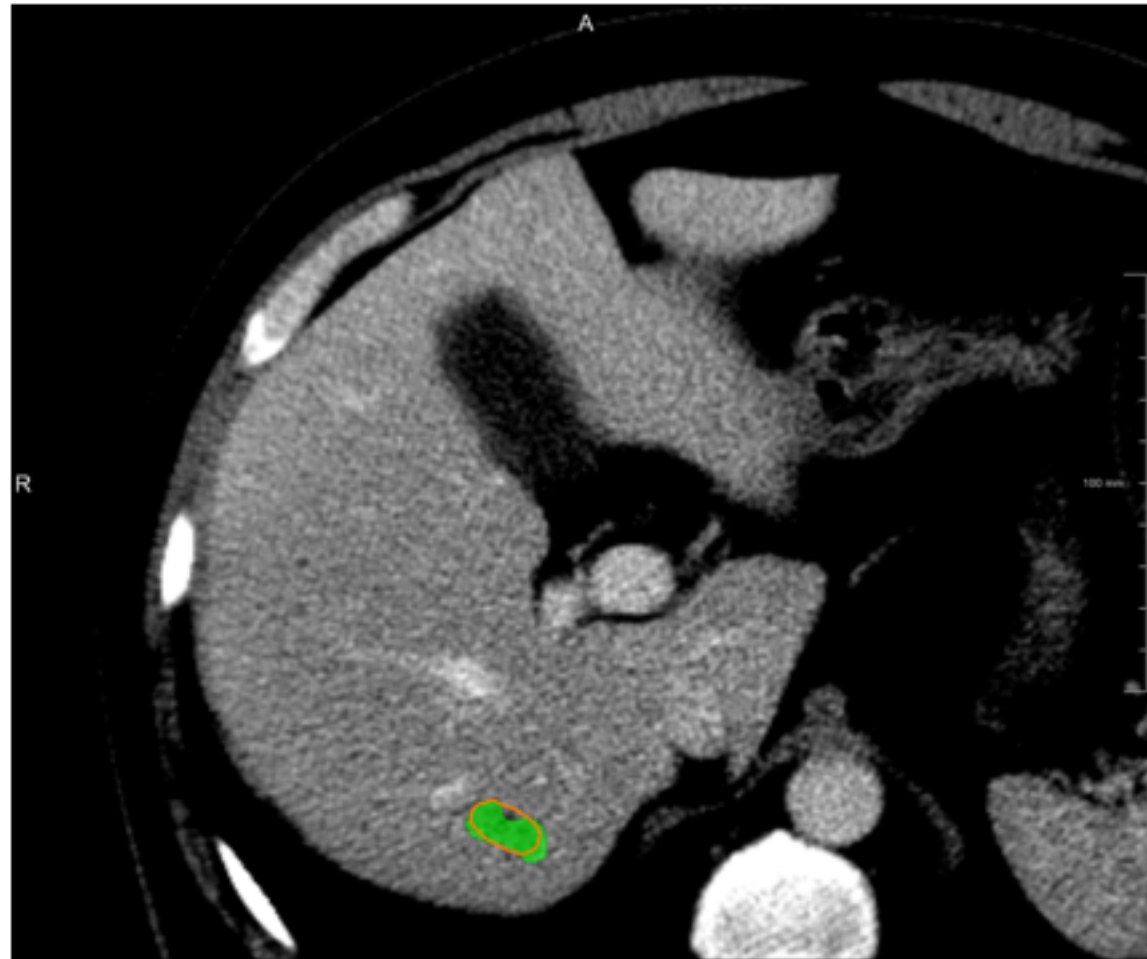


Without RF-Postprocessing

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Tumor Segmentation

FPs Filtering Examples



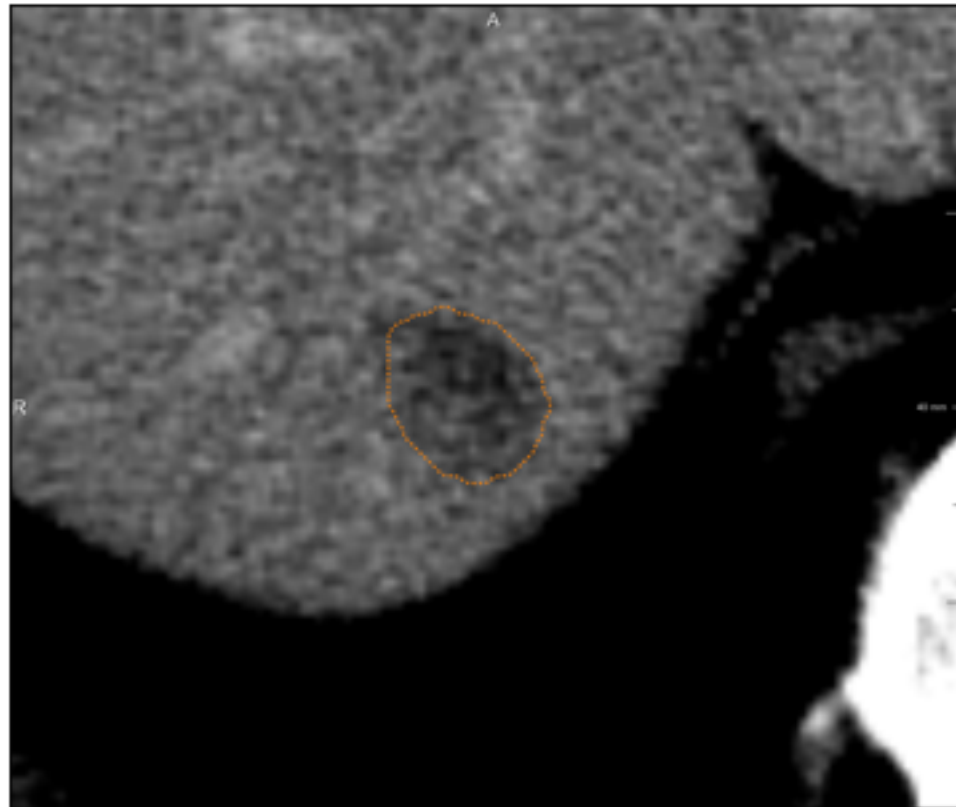
With RF-Postprocessing

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Tumor Segmentation

FPs Filtering with Tumor Refinement

- Use tumor candidates to initialize stroke-based semi-automatic segmentation tool [2]



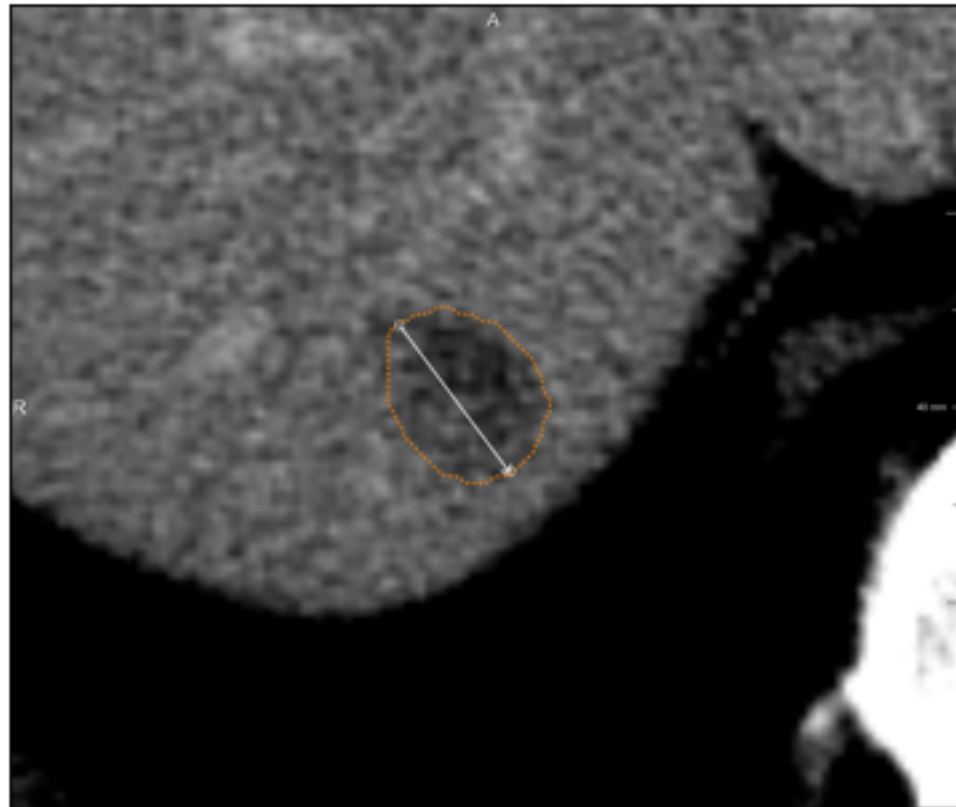
[2] Moltz J.H. et al., "Advanced segmentation techniques for lung nodules, liver metastases, and enlarged lymph nodes in CT scans", 2009.

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Tumor Segmentation

FPs Filtering with Tumor Refinement

- Use tumor candidates to initialize stroke-based semi-automatic segmentation tool [2]



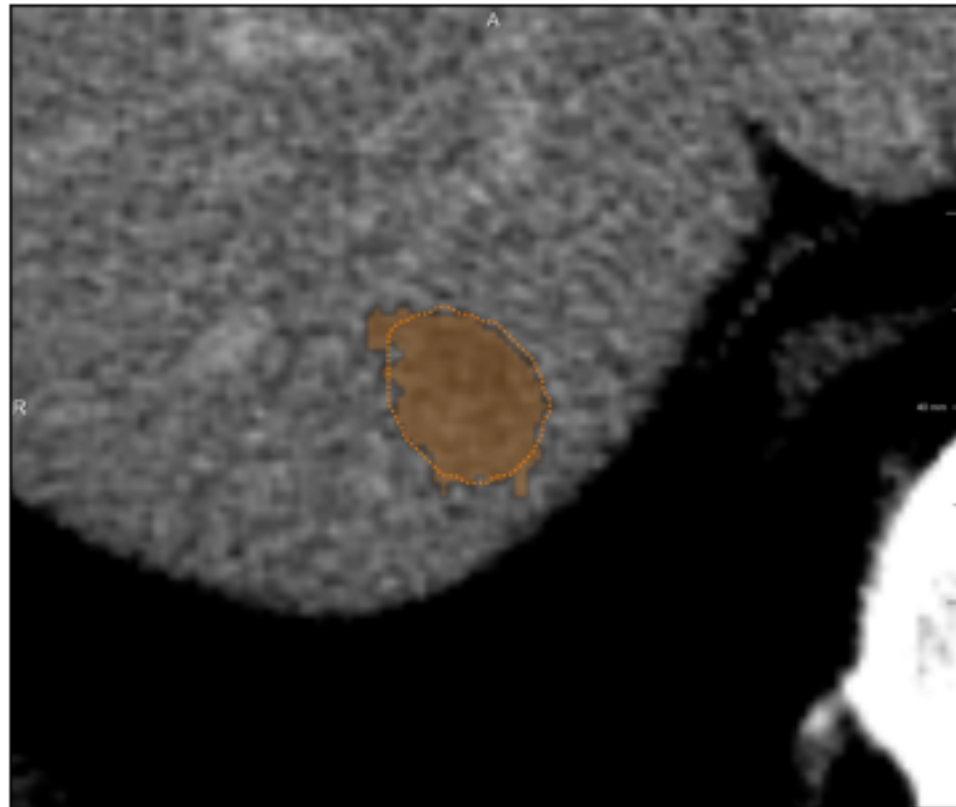
[2] Moltz J.H. et al., "Advanced segmentation techniques for lung nodules, liver metastases, and enlarged lymph nodes in CT scans", 2009.

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Tumor Segmentation

FPs Filtering with Tumor Refinement

Stroke application

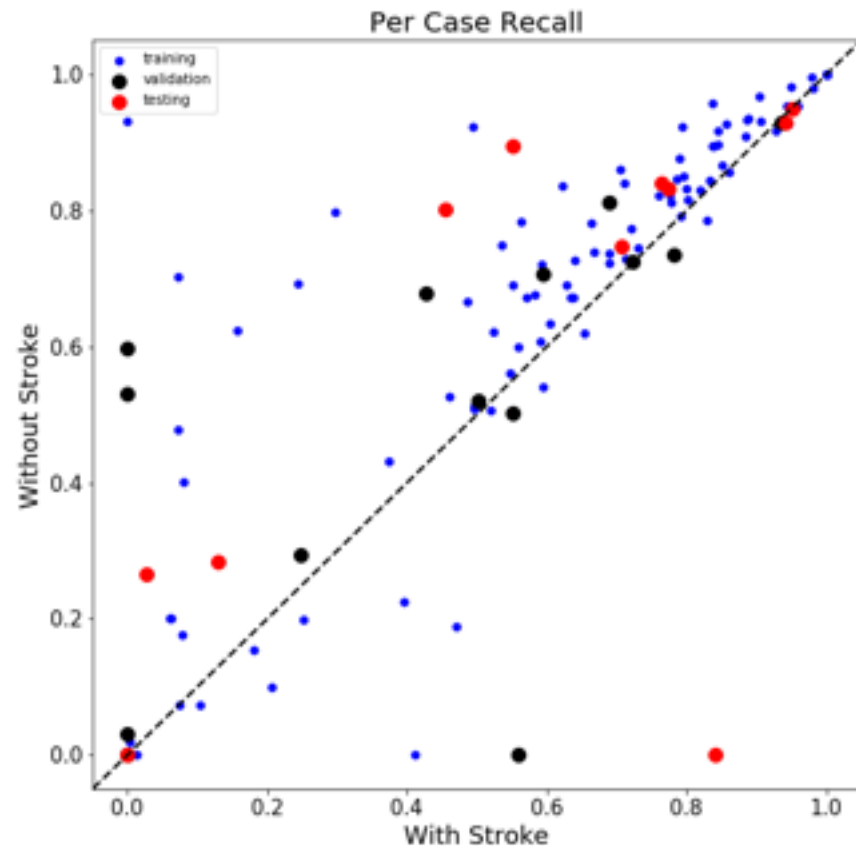
- Segmentation refinement
- Additional features for RF classifier of the refined tumors

Tumor Segmentation

FPs Filtering with Tumor Refinement

Stroke application



- Segmentation refinement
- Additional features for RF classifier of the refined tumors
- Stroke vs No-Stroke:
 - Recall

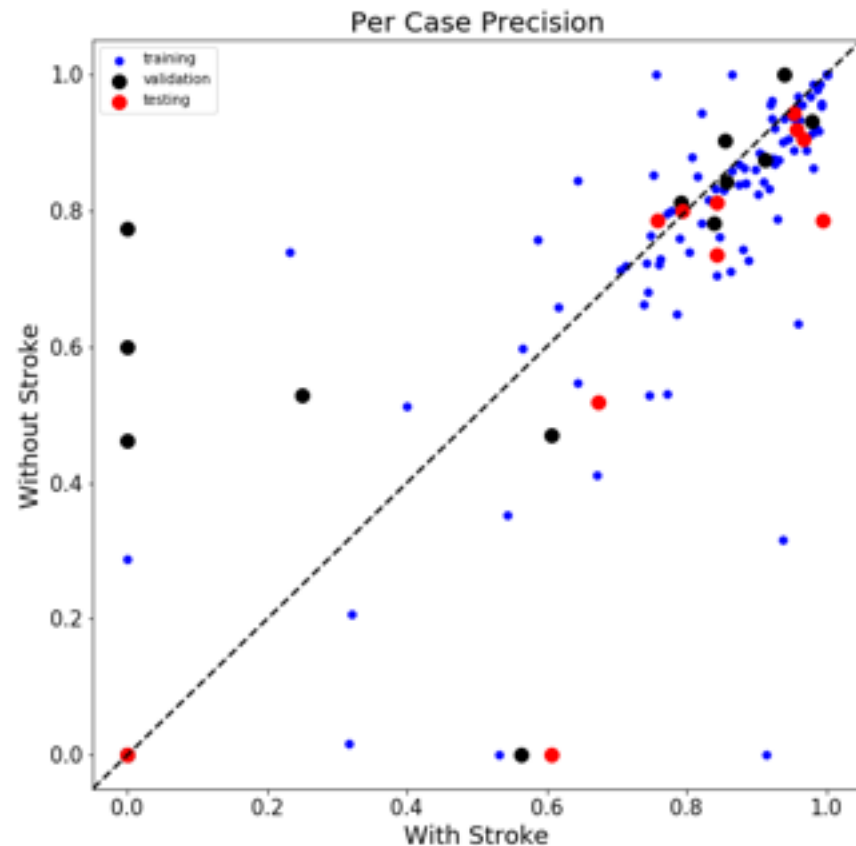


Tumor Segmentation

FPs Filtering with Tumor Refinement

Stroke application

- Segmentation refinement
- Additional features for RF classifier of the refined tumors
- Stroke vs No-Stroke:
 - Recall 
 - Precision 






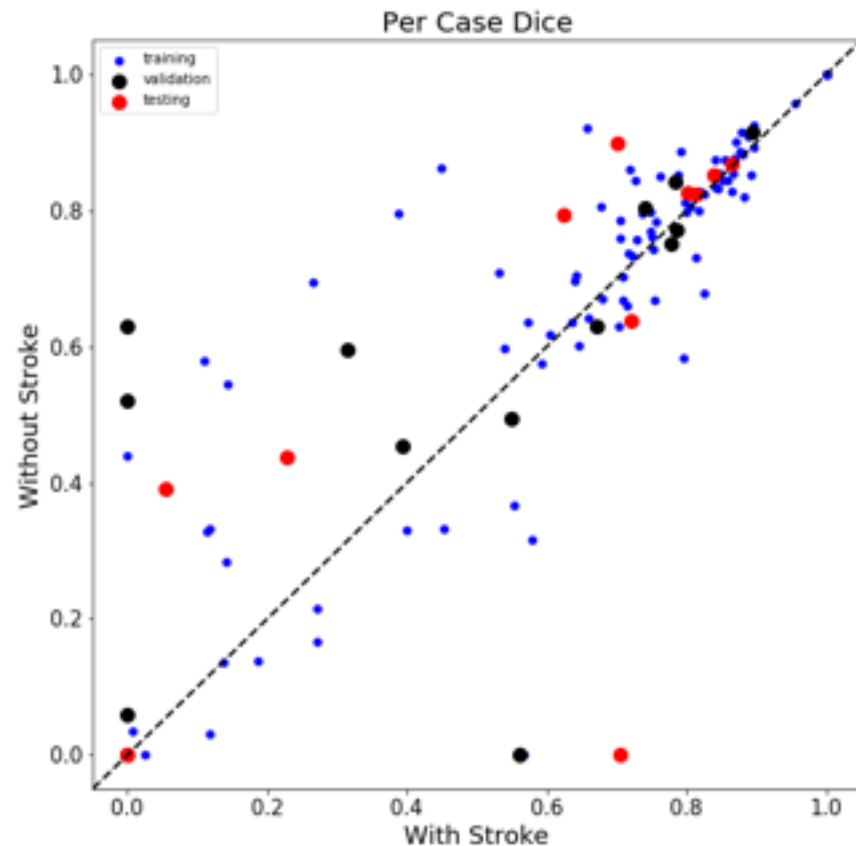
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Tumor Segmentation

FPs Filtering with Tumor Refinement

Stroke application

- Segmentation refinement
- Additional features for RF classifier of the refined tumors
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 - Precision 
 - Dice 



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2.5D FCN Architecture

Idea:


- Add more context information
- 1st LiTS round winner used 2.5D [3]

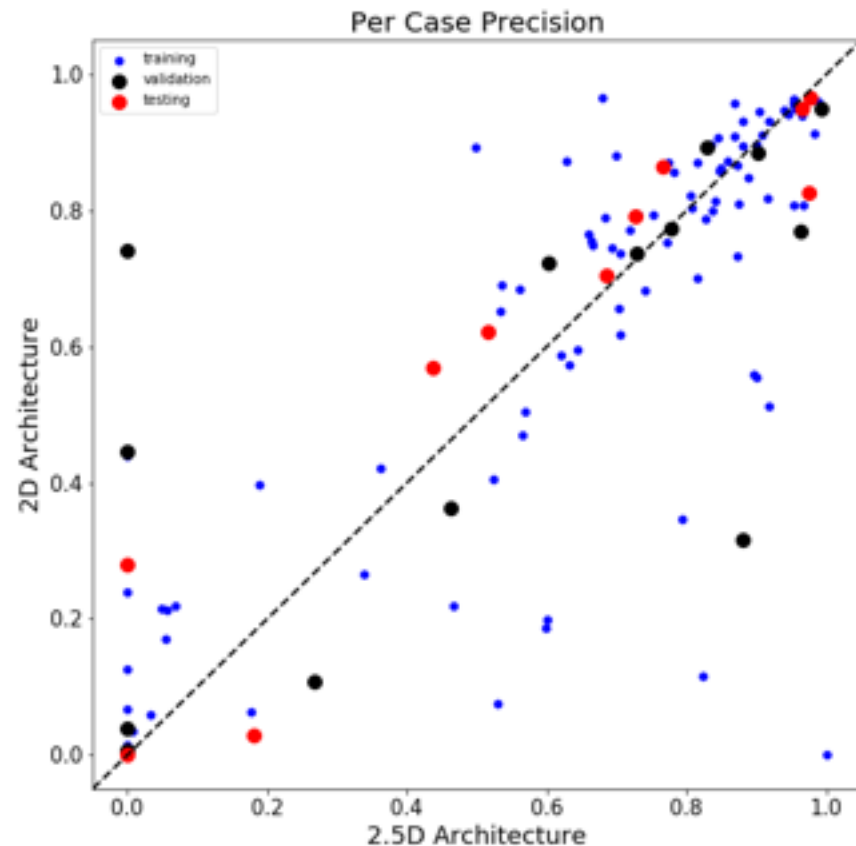
[3] Han X. "Automatic Liver Lesion Segmentation Using A Deep Convolutional Neural Network Method." 2017.

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2.5D FCN Architecture

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- 2.5D vs 2D:
 - Precision 





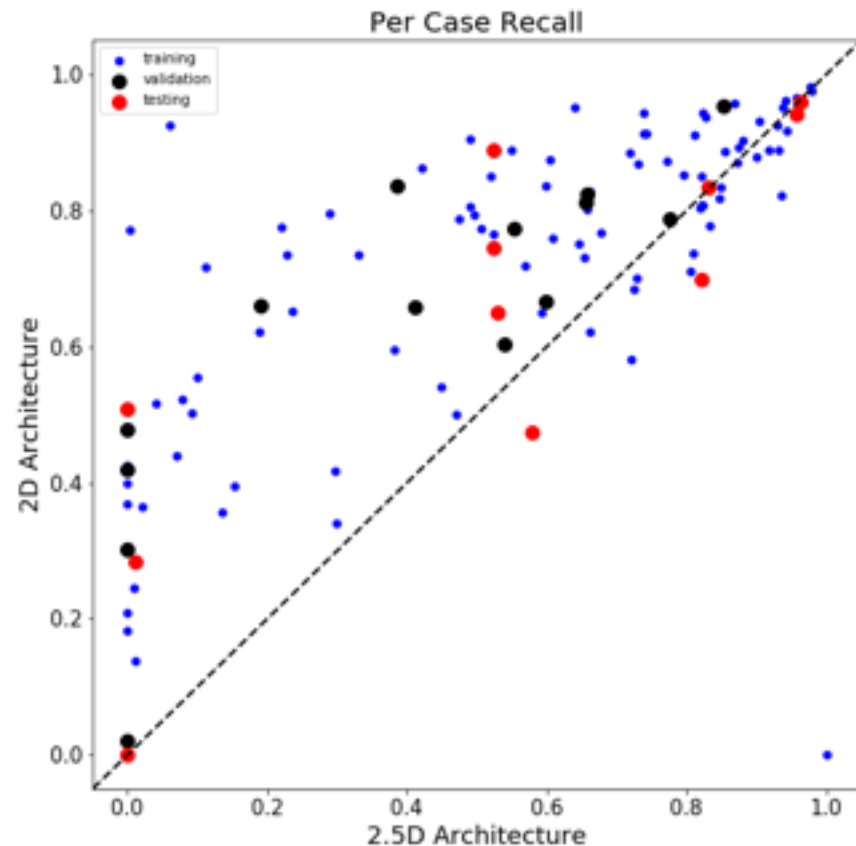
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2.5D FCN Architecture

Idea:

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■ 2.5D vs 2D:

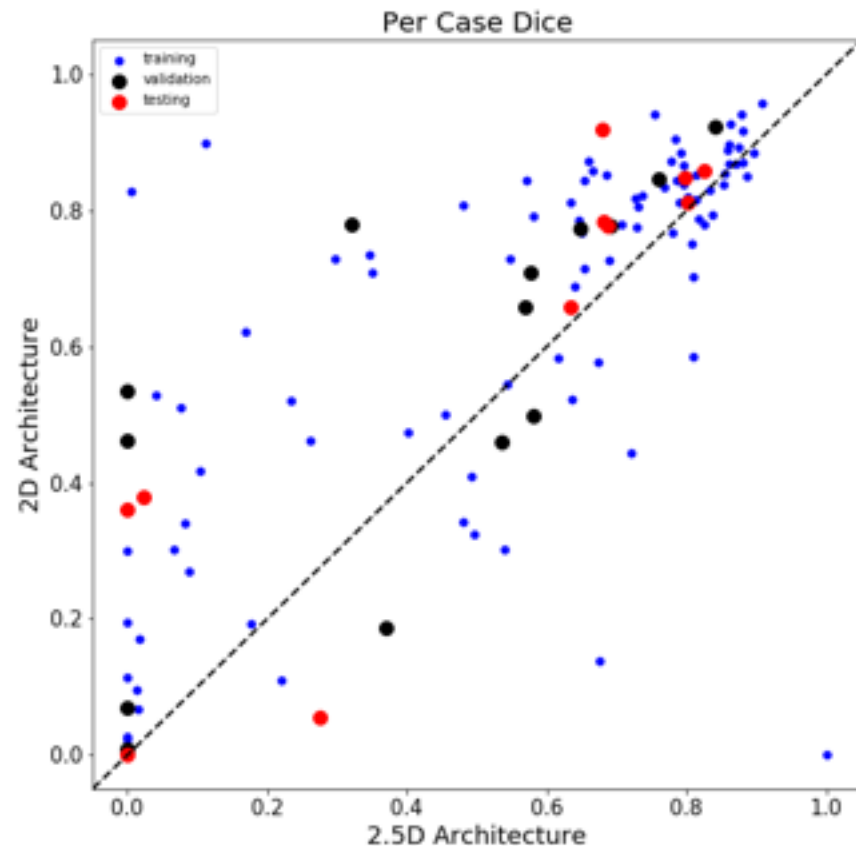
■ Precision



■ Recall



■ Dice






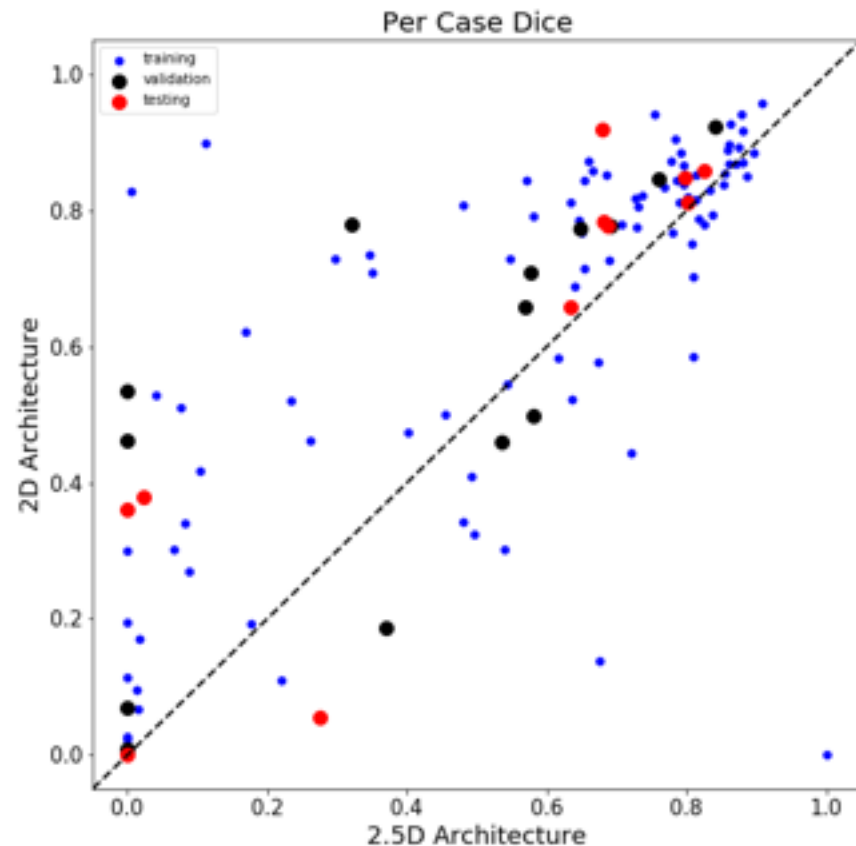
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2.5D FCN Architecture

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- 2.5D vs 2D:
 - Precision 
 - Recall 
 - Dice 
- Same observations for liver!



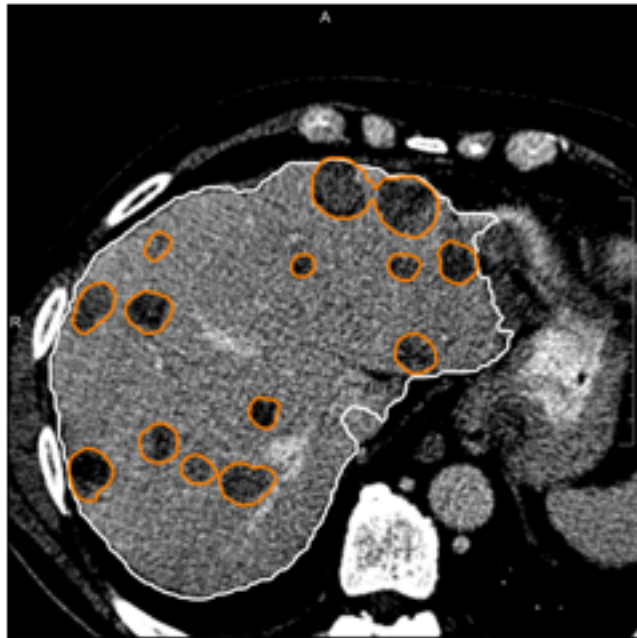
[3] Han X. "Automatic Liver Lesion Segmentation Using A Deep Convolutional Neural Network Method." 2017.

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Examples

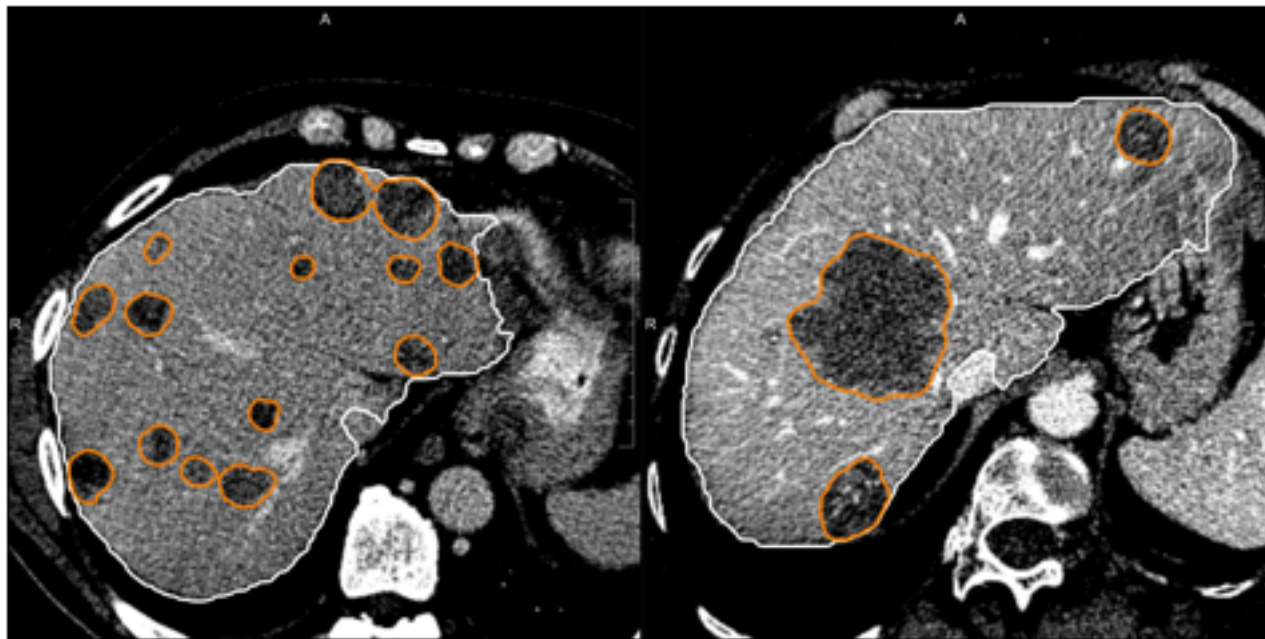
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Examples



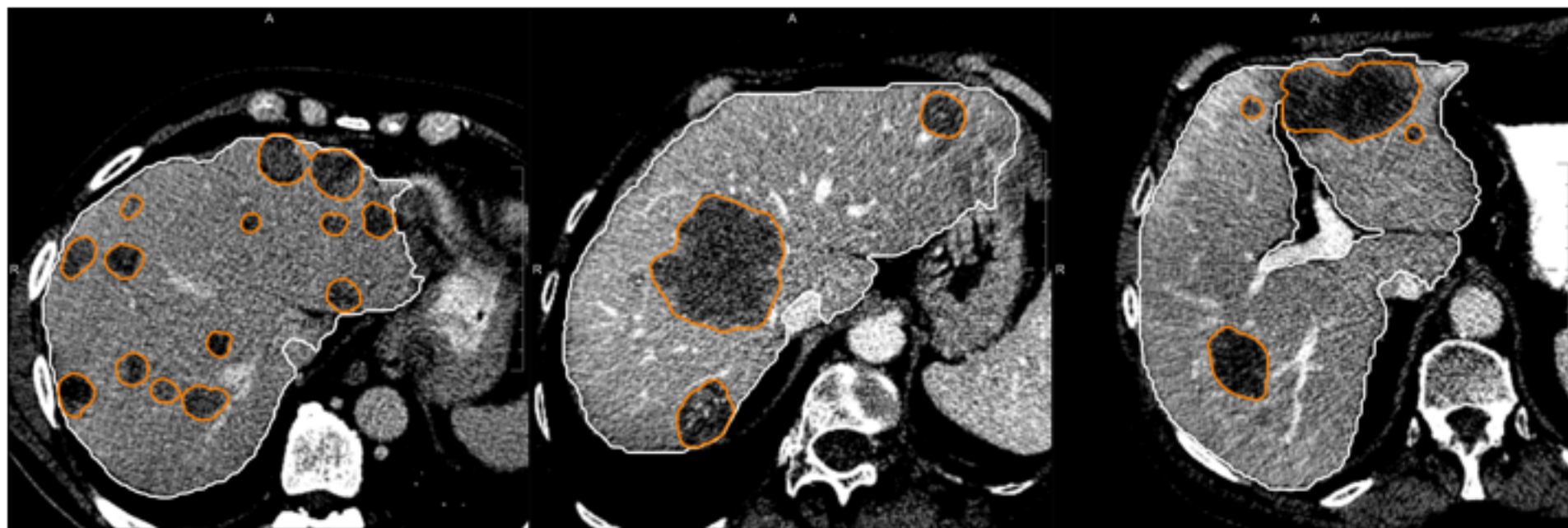
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Examples



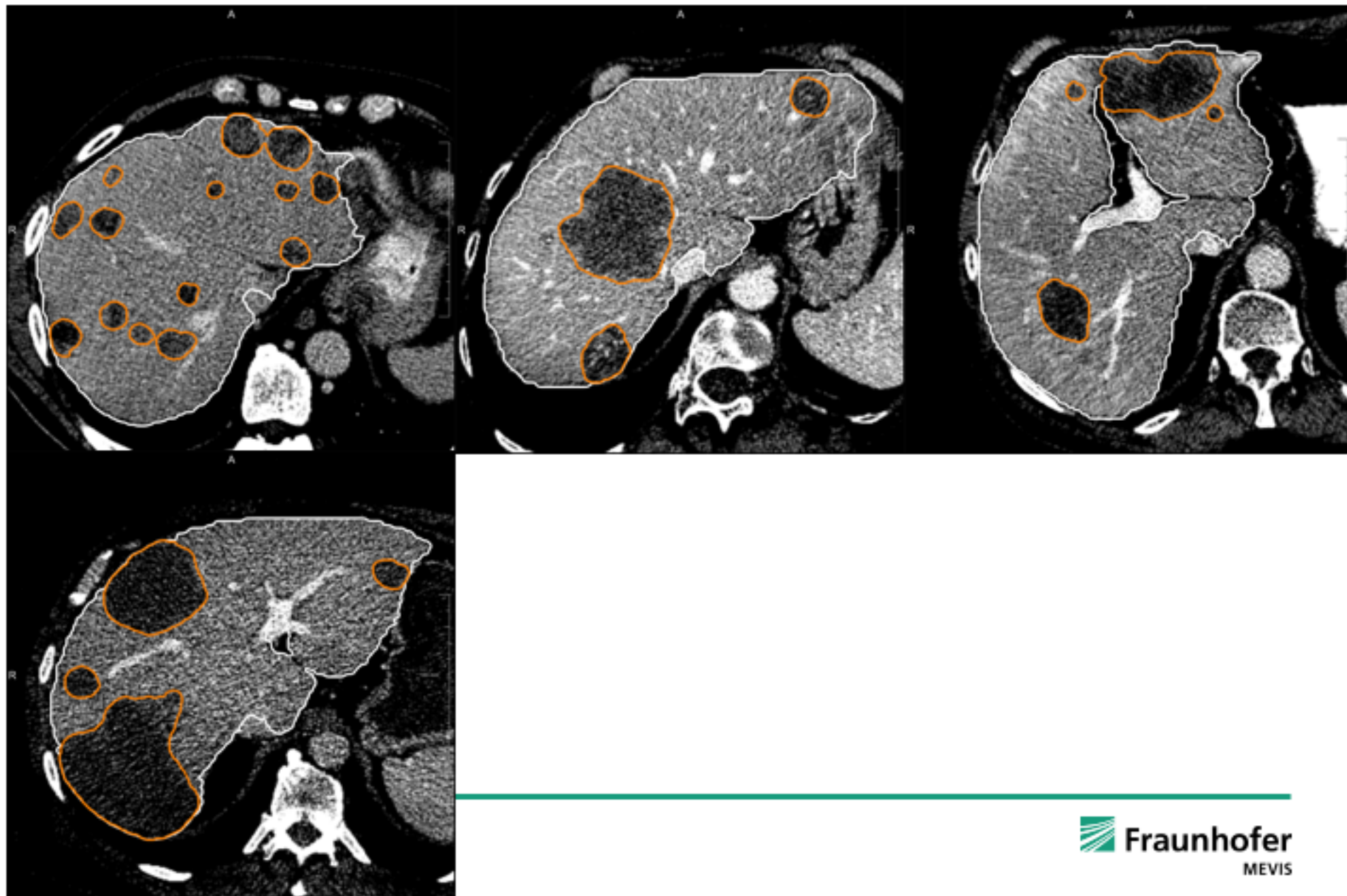
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Examples

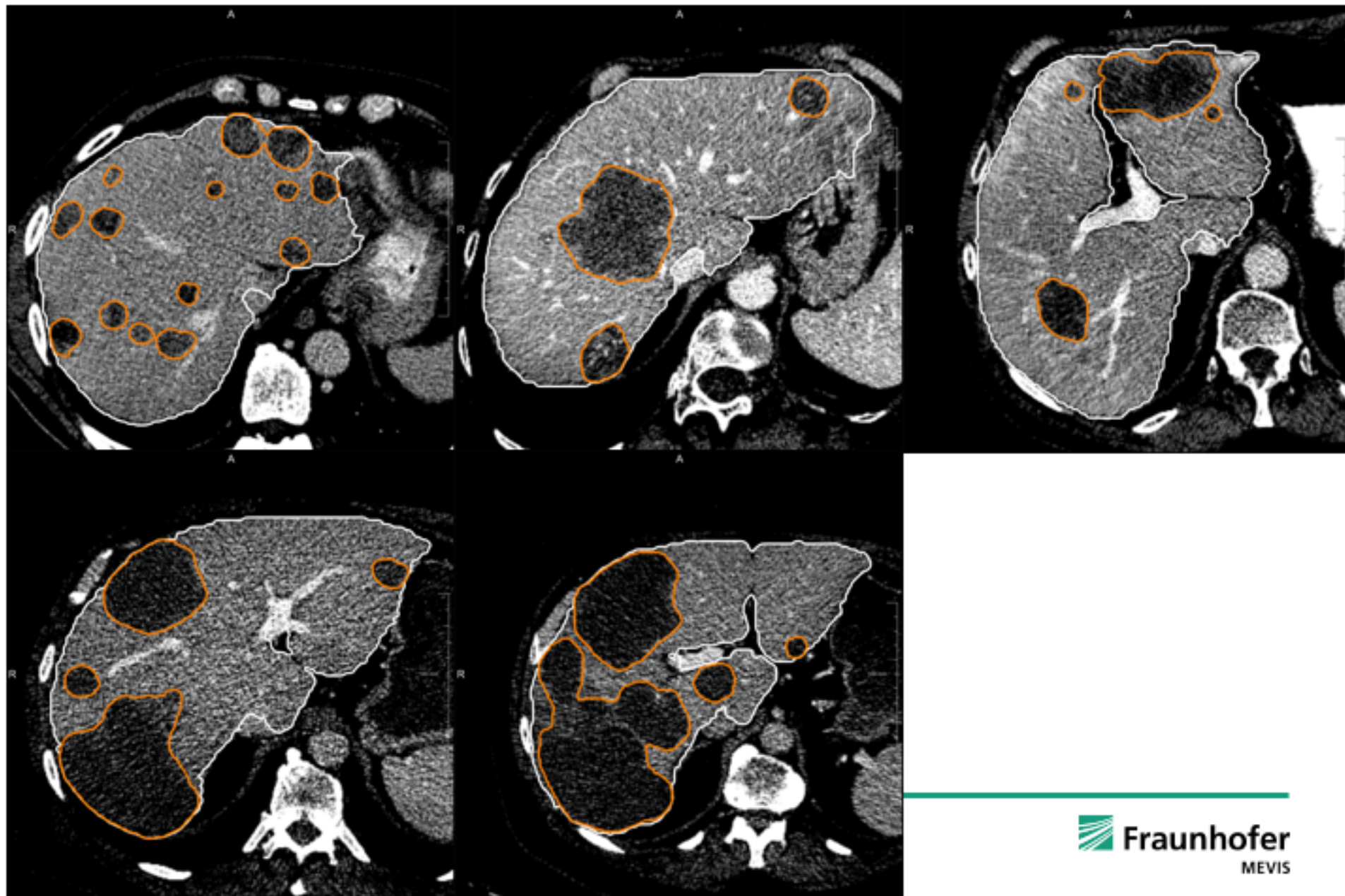


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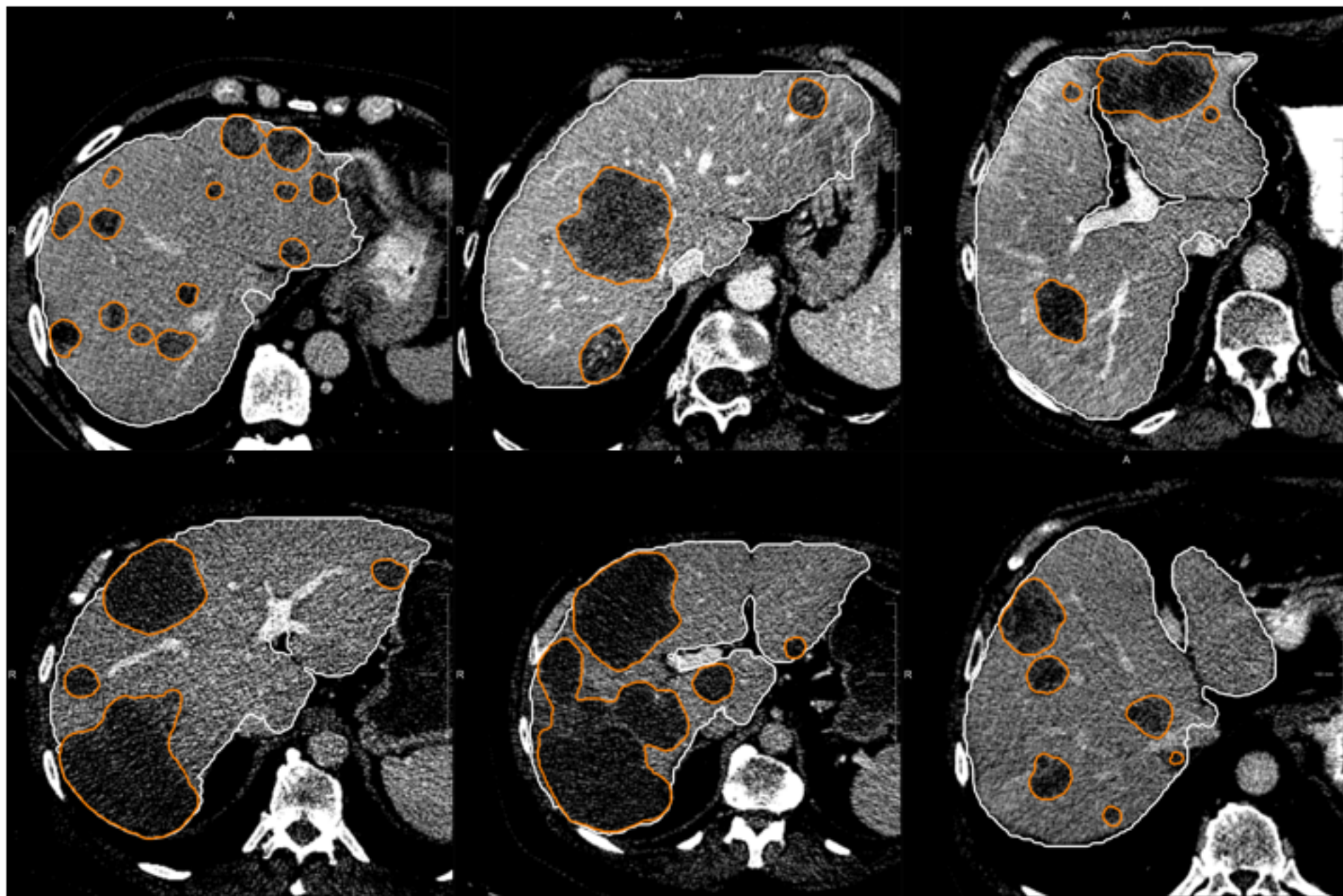
Examples



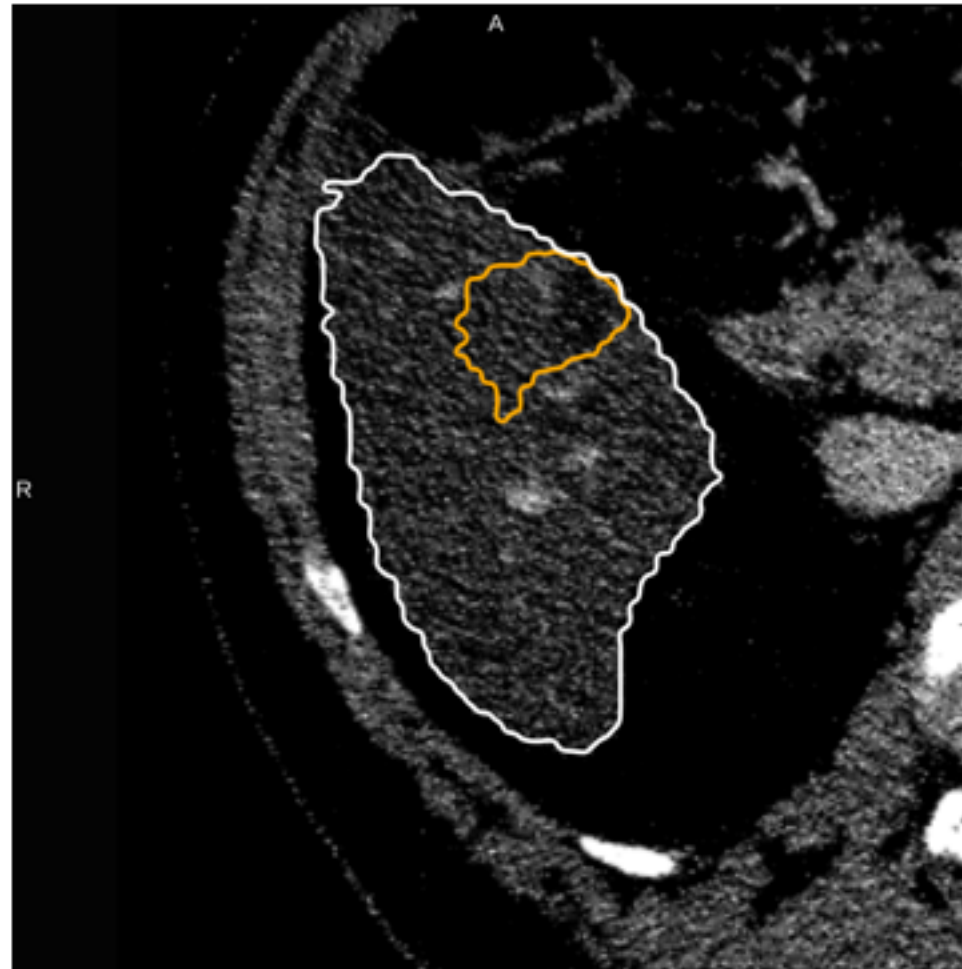
Examples



Examples



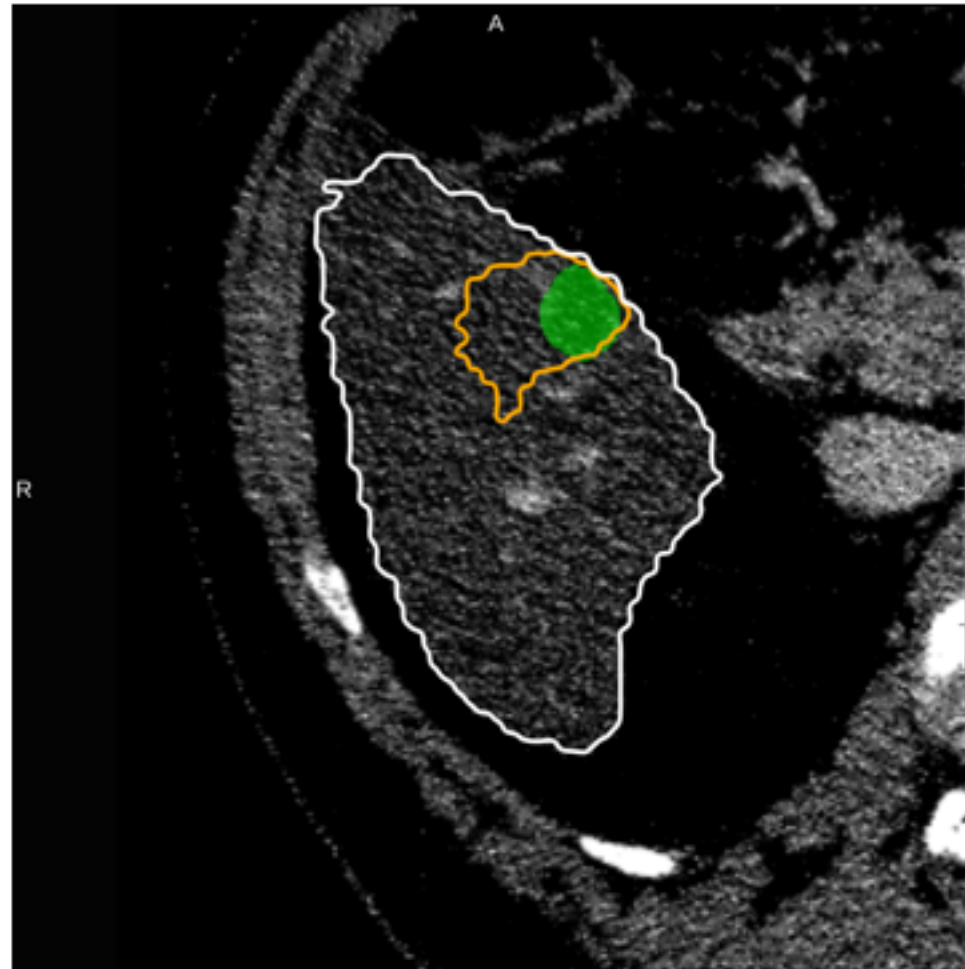
Problematic Cases



- Found tumor bigger than the reference

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Problematic Cases



- Found tumor bigger than the reference

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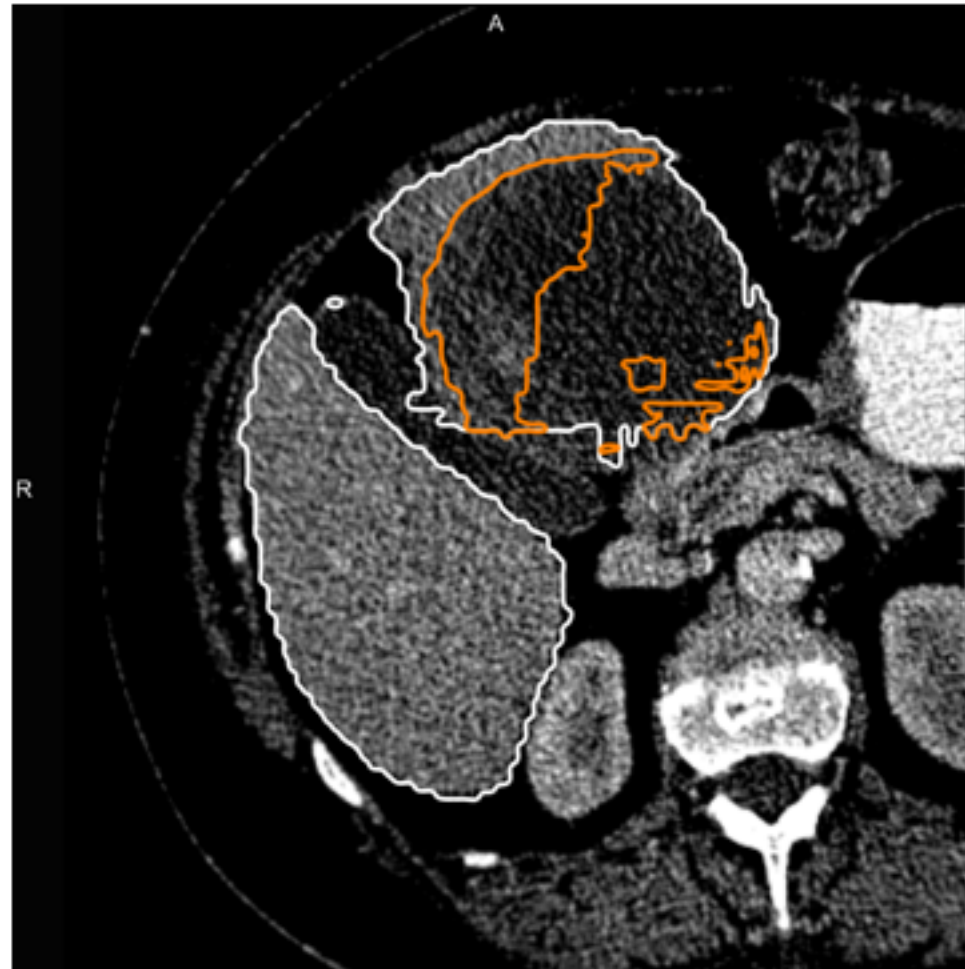
Problematic Cases



- Liver mask misses tumors located near organ's border

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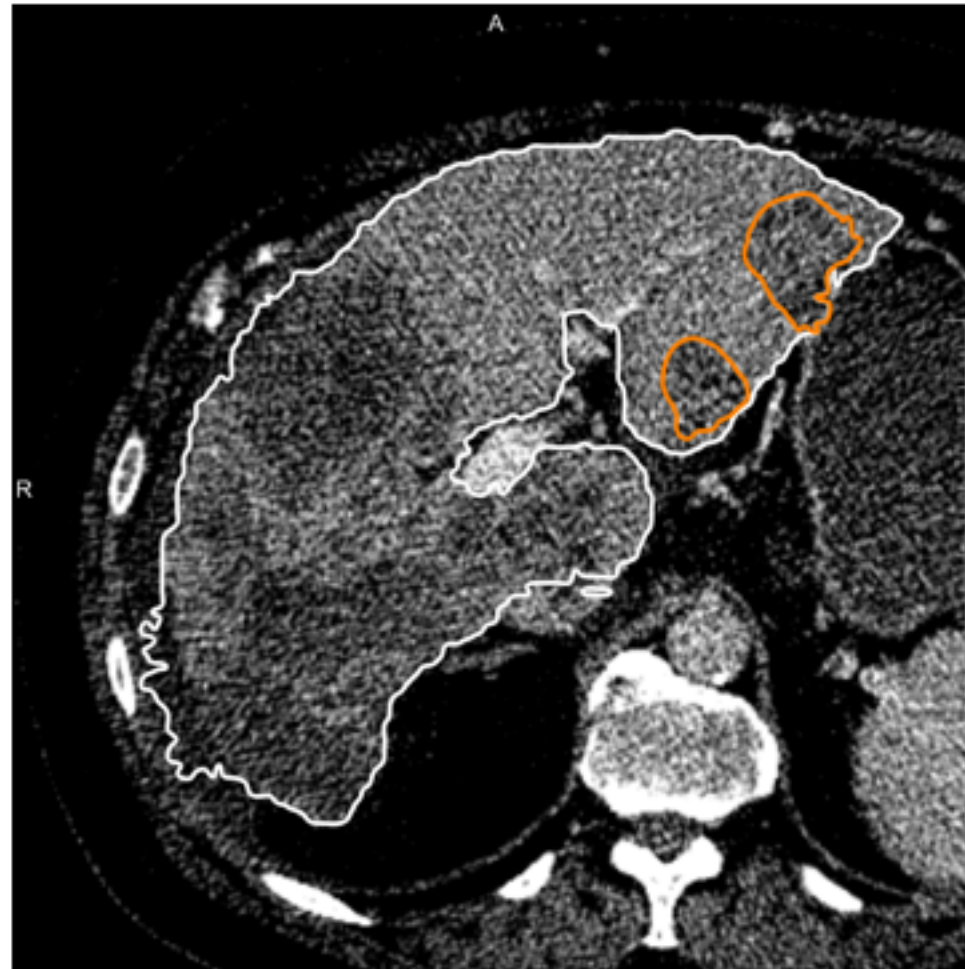
Problematic Cases



- Big tumors are not fully segmented

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Problematic Cases



- Obvious(?) tumors are completely missed

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LiTS Results

- Liver segmentation
 - Dice per case: 0.96
 - Relative volume difference: -0.4%

LiTS Results

- Liver segmentation
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- Tumor segmentation
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 - Recall at > 0% overlap: 0.57

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 - RMSE: 0.02
 - Max: 0.07

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 - Max: 0.07
- Inference time per CT volume: ~2 min on GTX 1080
 - Liver segmentation: ~43 s
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 - FPs filtering: ~19s

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OK



**Further work
required**

Technical Setup

- Data loading and preprocessing

- MeVisLab



- Deep Learning Toolkits

- RedLeaf
- Lasagne
- Theano



theano

- Evaluation

- Challengr



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Conclusions

- We proposed a fully automatic method for liver and liver lesion segmentation based on FCNs
- False positive tumors were filtered with a high accuracy using image intensity and shape based features
- Providing more context to the network (2.5D) decreased the segmentation quality
- Further work is required to make tumor segmentation clinically applicable

Outlook

- Different architectures
 - Adversarial networks
 - Recurrent networks
- Other training strategies
 - Curriculum learning



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Outlook

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Thank you for your attention 😊
Questions?

